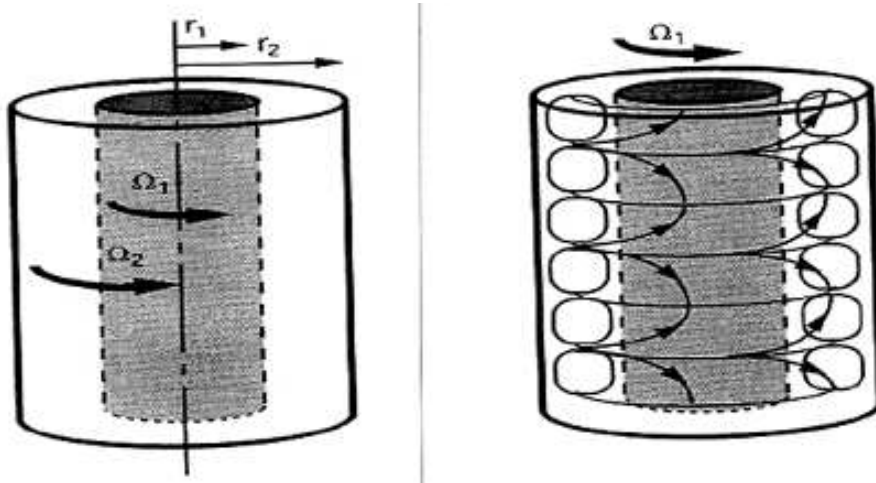


Nonlinear Saturation of Centrifugal Instability in Inviscid Taylor-Couette Flow

Mark Fruman and T. G. Shepherd
Department of Physics
University of Toronto
mfruman@atmosp.physics.utoronto.ca

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(from Tagg, 1994. Nonlin. Sci. Today)



History

- [Rayleigh \(1916\)](#): inviscid stability requires that angular momentum increases away from axis of rotation
- [Taylor \(1923\)](#): linear stability curve of corresponding viscous problem asymptotes to Rayleigh line in the limit of high Re
- [Joseph and Hung \(1971\)](#): nonlinear asymptotic stability of viscous problem shown for *near rigid body* conditions (nonlinear extension of [Synge, 1938](#))

from:

Joseph, D. D. *Stability of Fluid Motions*.
Springer-Verlag, 1976

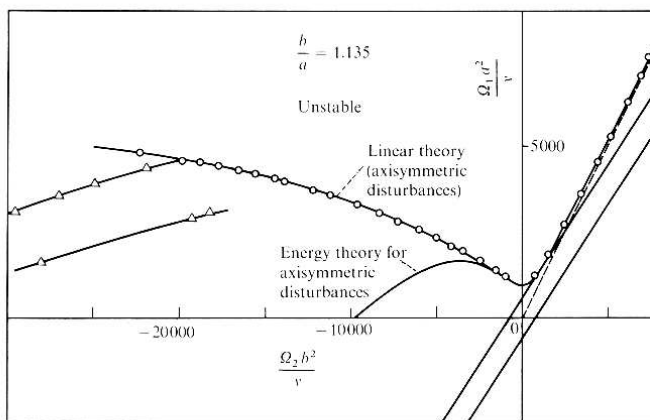


Fig. 37.1.a: Stability regions for Couette flow between rotating cylinders. The circles and triangles are observed points of instability in the experiments of D. Coles (1965) (Joseph and Hung, 1971)

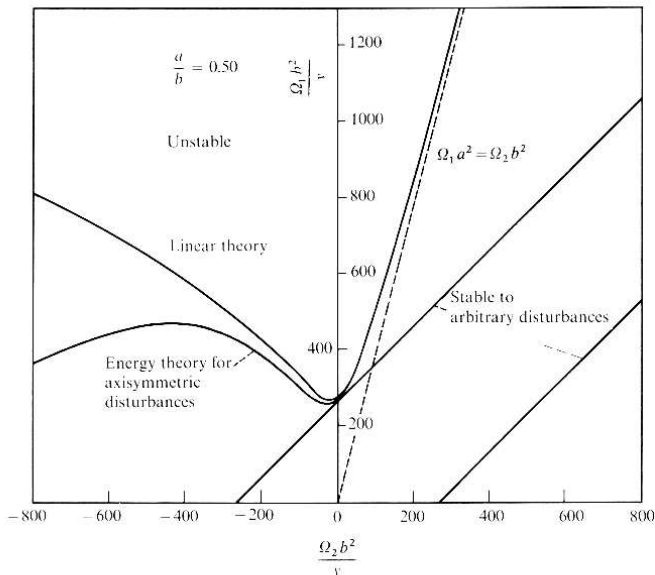


Fig. 37.1.b: Stability regions for Couette flow between rotating cylinders (Joseph and Hung, 1971)

Definitions

- Parameters: $\eta \equiv \frac{r_1}{r_2}$ and $\mu \equiv \frac{\Omega_2}{\Omega_1}$

- Equations nondimensionalized such that

$$\begin{aligned} r_1 &\equiv 1 & \Omega_1 &\equiv 1 \\ r_2 &= \eta^{-1} & \Omega_2 &= \mu \end{aligned}$$

-
- Fluid velocity in cylindrical coordinates:

$$\mathbf{v} = u\hat{\mathbf{e}}_r + v\hat{\mathbf{e}}_\theta + w\hat{\mathbf{e}}_z$$

Angular momentum: $m \equiv rv$

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- State vector:

$$\mathbf{x}(r, z, t) \equiv (u(r, z, t), m(r, z, t), w(r, z, t))^T,$$

- Couette (equilibrium) profile:

$$\mathbf{X}(r) \equiv (0, M(r), 0)^T$$

Nonlinear Stability of Couette Profile

We consider stability of Couette profile

$$M(r) = Ar^2 + B$$

under axisymmetric perturbations. All steady flows in corresponding viscous problem have profile $M(r)$. Here, we consider the inviscid case as a model for high Re flow.

Constants A and B determined by *no-slip* condition on surfaces of cylinders:

$$A = \frac{\mu - \eta^2}{1 - \eta^2}, \quad B = \frac{1 - \mu}{1 - \eta^2}$$

Method based on conservation of kinetic energy:

$$\mathcal{H} = \iint \frac{1}{2} |\mathbf{v}|^2 r dr dz$$

and all integrals of the form (Casimirs)

$$\mathcal{C} = \iint C(m) r dr dz$$

where $C(m)$ is any differentiable function.

Choose function $C(m)$ so that **first variation** of combination $\mathcal{H} + C$ vanishes when evaluated at equilibrium:

$$\delta(\mathcal{H} + C)|_{\mathbf{X}} = 0$$

(so that \mathbf{X} is a **critical point** of $\mathcal{H} + C$).

This is achieved if, for $m \in \text{range}[M(r)]$,

$$C'(m) = \frac{-Am}{m - B}$$

Outside of $\text{range}[M(r)]$, we may extend $C'(m)$ in any way, so long as it is continuous.

Define **pseudoenergy** as the departure of $\mathcal{H} + C$ from its equilibrium value. We may write it in the form

$$\begin{aligned} \mathcal{A}(\mathbf{x}, \mathbf{X}) = & \iint \frac{1}{2} \{u^2 + w^2 \\ & + \frac{1}{r} [1 + r^2 C''(\tilde{m})] (m - M)^2\} r dr dz \end{aligned}$$

where $\tilde{m}(r, z, t) \in [M(r), m(r, z, t)]$.

Can claim stability of \mathbf{X} if $0 < \mathcal{A}(\mathbf{x}, \mathbf{X}) < \infty \forall \mathbf{X}$.

This follows from conservation of \mathcal{A} , since

$$\|\Delta \mathbf{x}(t)\|^2 \leq \mathcal{A}(t) = \mathcal{A}(0) \leq \frac{\lambda_+}{\lambda_-} \|\Delta \mathbf{x}(0)\|^2$$

which implies that $\|\Delta \mathbf{x}\|$ is bounded for all time in terms of its initial value.

The norm is defined by

$$\|\Delta \mathbf{x}\|^2 \equiv \iint \frac{1}{2} [u^2 + w^2 + \frac{\lambda_-}{r^2} (m - M)^2] r dr dz,$$

and λ_- and λ_+ are the minimum and maximum values of

$$F(m, r) \equiv 1 + r^2 C''(m)$$

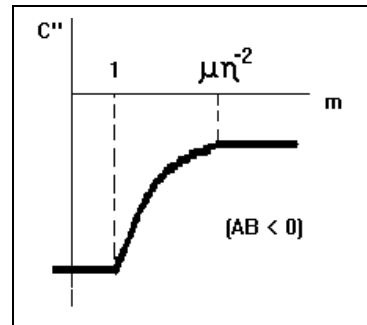
over all values of m and for all $r \in [1, \eta^{-1}]$.

To account for all possible perturbations, must define $C''(m)$ for all values of m . A simple choice is

$$C''(m) = \begin{cases} \frac{B}{A} & m < 1 \\ \frac{AB}{(m-B)^2} & 1 < m < \mu\eta^{-2} \\ \frac{AB}{(\mu\eta^{-2}-B)} & m > \mu\eta^{-2} \end{cases}$$

Notice that $F(m, r)$ can only be negative if $AB < 0$, in which case the least value of $F(m, r)$ obtains when r is maximized and $C''(m)$ is most negative.

Thus stability assured if



$$F(m = 1, r = \eta^{-1}) = \frac{[(\eta^2 + 1) - \mu](1 - \eta^2)}{\eta^2(\mu - \eta^2)} > 0$$

i.e. if $\eta^2 < \mu < \eta^2 + 1$. In dimensional form:

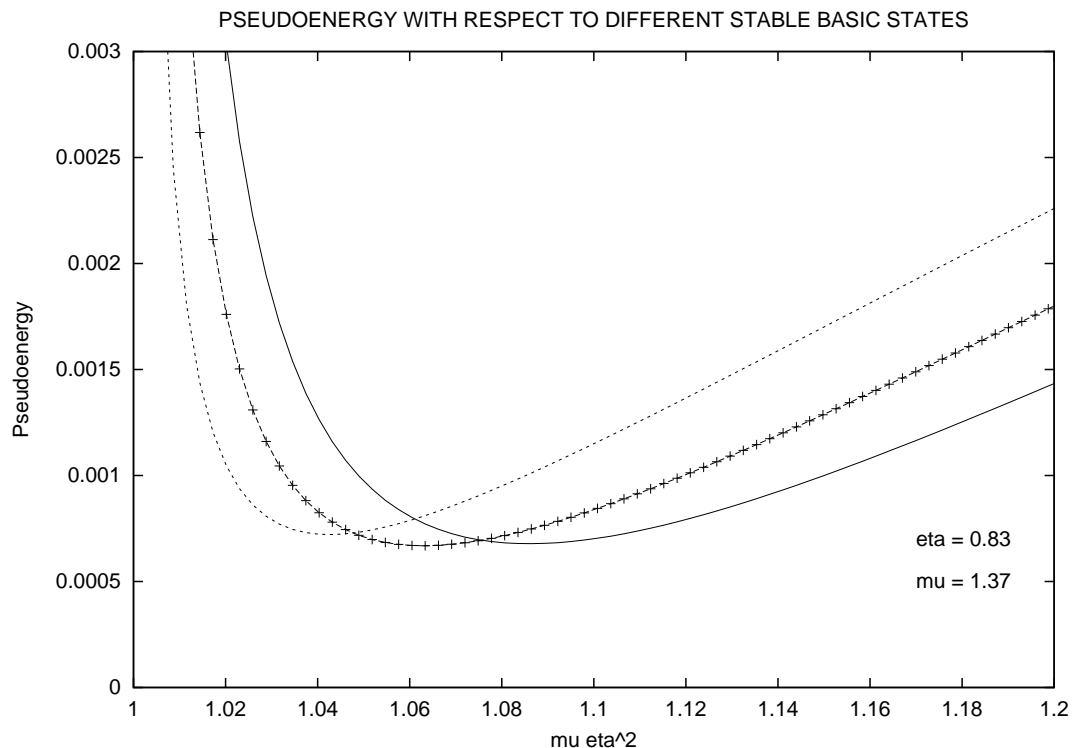
$$\left(\frac{r_1}{r_2}\right)^2 < \frac{\Omega_2}{\Omega_1} < \left(\frac{r_1}{r_2}\right)^2 + 1$$

Saturation of Disturbance Amplitude

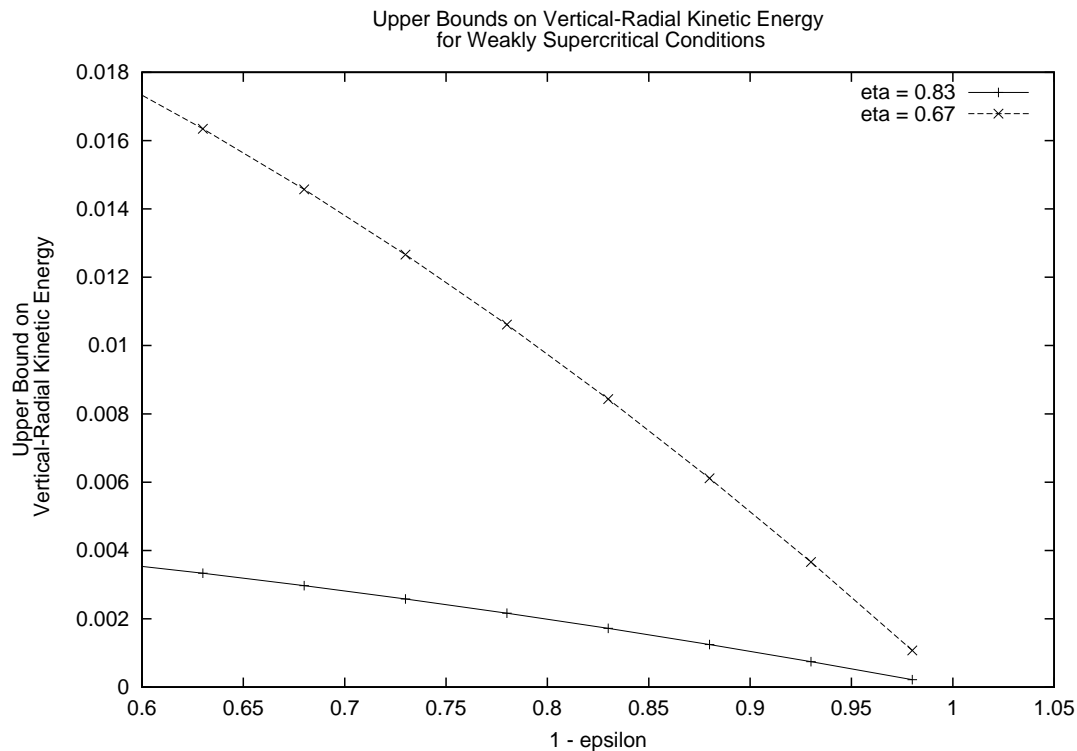
Since, relative to every stable \mathbf{X} , the pseudoenergy of every state \mathbf{x} is positive and conserved, the energy released into the overturning flow (e.g. Taylor vortex flow) from an unstable basic state is bounded from above via

$$\mathcal{K}(\mathbf{x}(t)) \equiv \iint \frac{1}{2}[u^2 + w^2]rdrdz \leq \mathcal{A}(\mathbf{x}(0), \mathbf{X}).$$

We consider unstable Couette equilibrium profiles with $\mu_u < \eta^2$ and compute their pseudoenergies relative to a range of stable profiles (characterized by μ and, say, Ω_1):



and we plot the minimum value of all pseudoenergies so obtained:



- Upper bound on $\min \mathcal{A}$ approaches zero as $\epsilon \equiv 1 - \mu\eta^2$ approaches bifurcation point. Hence, the amplitude to which an initially small perturbation can grow is bounded near zero near the critical value of ϵ (characteristic of supercritical bifurcation).
- Landau theory (amplitude equations): equilibrium amplitude $\sim \epsilon^{1/2} \Rightarrow$ energy $\sim \epsilon$

Summary

- Considering only axisymmetric disturbances, we demonstrate a nonlinear generalization to [Rayleigh](#)'s centrifugal stability condition.
- Growth of small disturbances to weakly supercritical equilibria are bound near zero, consistent with the existence of the stable axisymmetric Taylor vortex state, without the influence of viscosity.
- Hopefully, result can be extended to include viscosity; for example, showing that \mathcal{A} is bounded from above during the evolution from a perturbed state (this might complement asymptotic stability results of [Joseph and Hung](#), etc.)