

Chapter 32

Faraday's Law of Induction

32-1 Symmetries

A current carrying loop in an external mag. field \vec{B} feels a torque $\vec{\tau}$.

Current \longrightarrow Torque (Principle of electromotor)

If a conducting loop is rotated by exerting a torque $\vec{\tau}$ in an external mag. field, a current appears in the loop.

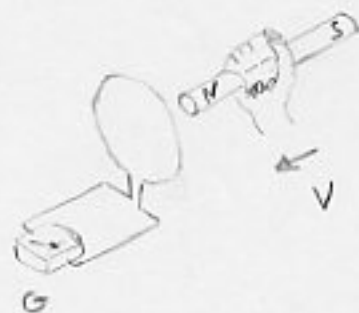
Torque \longrightarrow Current (Principle of electric generator)

This phenomenon is on the basis of Faraday's law of induction.

32-2 Two Experiments:

Deflection of galvanometer $\sim |V|$

The dir. of the deflection $\xrightarrow{\text{depends on}} \vec{V}$
" " " $\xrightarrow{\text{magnet pole}}$

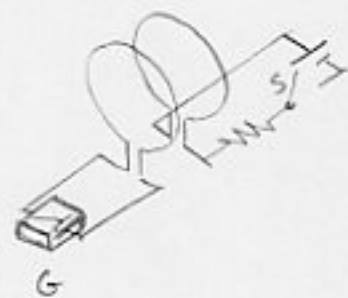


The appeared current in the loop is said to be an induced current.

The work done per unit charge in moving the charge of that current through the loop is said to be an induced emf.

Second Experiment

When we close or open the switch S an induced current appears in the second loop (momentarily) but in opposite dir.



Conclusion:

An emf is induced only when something is changing. In a static situation, in which no physical objects are moving and the currents are steady, there is no induced emf. The key word is change.

32-3 Faraday's Law of Induction

An emf is induced in the loop depends on the change of the field lines through the loop (the number of lines) and the rate of this change.

A Quantitative Treatment:

Consider a surface — which may or may not be a plane — bounded by a closed conducting loop.

$$\Phi_B = \int \mathbf{B} \cdot d\mathbf{A} \quad \text{magnetic flux} \quad \sim \text{number of mag. lines}$$

For a planar (flat) surface with $\mathbf{B} \perp \mathbf{A}$;

$$\Phi_B = BA$$

unit: $1 \text{ Weber} = 1 \text{ Wb} = 1 \text{ T} \cdot \text{m}^2$

Faraday's law:

$$\mathcal{E} = - \frac{d\Phi_B}{dt} \quad (\text{volts})$$

For N turns:

$$\mathcal{E} = - N \frac{d\Phi_B}{dt} \quad (\text{Faraday's law})$$

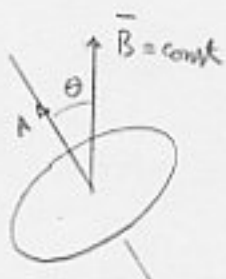
1- In Fig (a) if \vec{B} increases
in magnitude: $\Phi_B > 0$

also $\frac{d\Phi_B}{dt} > 0 \rightarrow \mathcal{E} < 0$



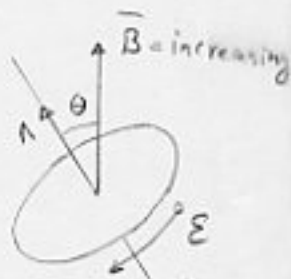
$\Phi_B = 0$

(a)



$\Phi_B > 0$

(b)



$\frac{d\Phi_B}{dt} > 0$

(c)

2- In Fig (c) if \vec{B} decreases

in magnitude: $\Phi_B > 0$

but $\frac{d\Phi_B}{dt} < 0 \rightarrow \mathcal{E} > 0$

3- \vec{B} points in the dir opposite that shown in Fig (c) and is

increasing in magnitude: $\Phi_B < 0$ and $\frac{d\Phi_B}{dt} < 0$

$\rightarrow \mathcal{E} > 0$

4- \vec{B} points in the dir opposite that shown in Fig (c)

and is decreasing in magnitude: $\Phi_B < 0$ and $\frac{d\Phi_B}{dt} > 0$

$\rightarrow \mathcal{E} < 0$

Ex.

A long solenoid has $n = 220$ turns/cm and carries $i = 1.5$ A, its diameter D is 3.2 cm. At its center we place a 130-turn close-packed coil C of diameter $d = 2.1$ cm. The current in the solenoid is reduced to zero and then increased to 1.5 A in the

other dir. at a steady rate over a period $T = 50 \text{ ms}$.

What is the magnitude of the induced emf that appears in the central coil while the current in the solenoid is being changed?

Sol.

$$|\mathcal{E}| = \frac{N \Delta \Phi_B}{\Delta t}$$

N : number of turns in the inner coil C .

$$B = \mu_0 i n = (4\pi \times 10^{-7} \text{ T}\cdot\text{m/A}) (1.5 \text{ A}) (220 \frac{\text{turns}}{\text{cm}} \times 100 \frac{\text{cm}}{\text{m}}) = 4.15 \times 10^{-2} \text{ T}$$

$$A_c = \pi \left(\frac{d}{2}\right)^2 = 3.46 \times 10^{-4} \text{ m}^2$$

Max B due to i produced by solenoid at its center

$$\Phi_B = B A_c$$

$$\Phi_B = B A_c = (4.15 \times 10^{-2} \text{ T}) (3.46 \times 10^{-4} \text{ m}^2) = 1.44 \times 10^{-5} \text{ Wb}$$

Φ_B changes sign but not magnitude as the current is reversed

$$\rightarrow \Delta \Phi_B = 2 \times 1.44 \times 10^{-5} = 2.88 \times 10^{-5} \text{ Wb}$$

$$|\mathcal{E}| = \frac{N \Delta \Phi_B}{\Delta t} = \frac{(130 \text{ turns}) (2.88 \times 10^{-5} \text{ Wb})}{50 \times 10^{-3} \text{ s}} = 7.5 \times 10^{-2} \text{ V}$$



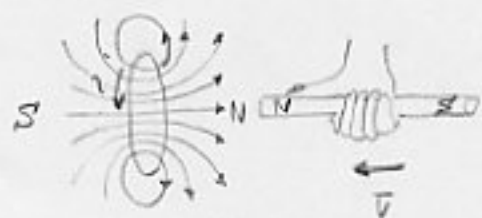
32-4 Lenz's law

An induced current in a closed conducting loop will appear in such a direction that it opposes the change that produced it.

The minus sign in $\mathcal{E} = -\frac{d\phi}{dt}$ carries with it this symbolic notion of opposition.

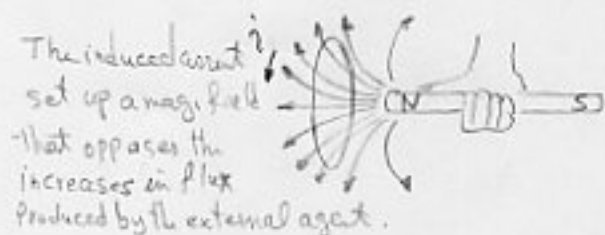
By the dir. of current we can find the dir of \mathcal{E} .

1- First Interpretation;

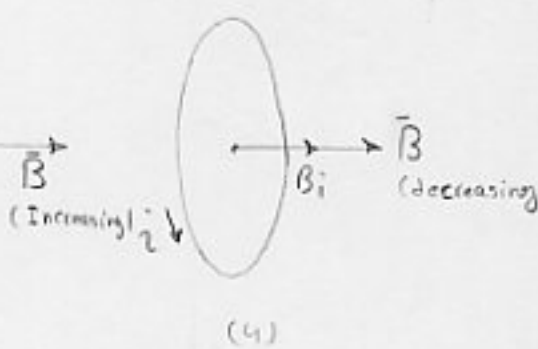
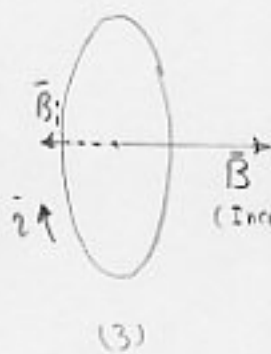
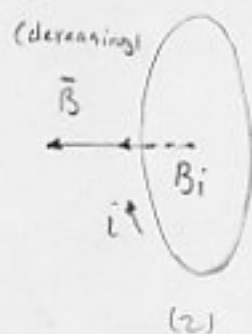
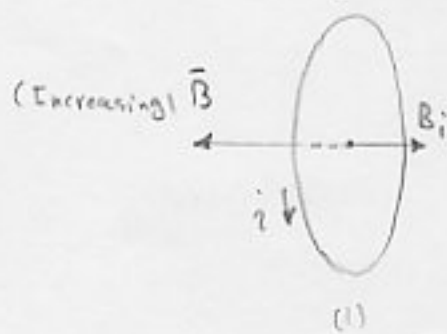


The induced current set up a mag. field that opposes the motion of magnet.

2- Second Interpretation;



The induced current set up a mag. field that opposes the increases in flux produced by the external agent.



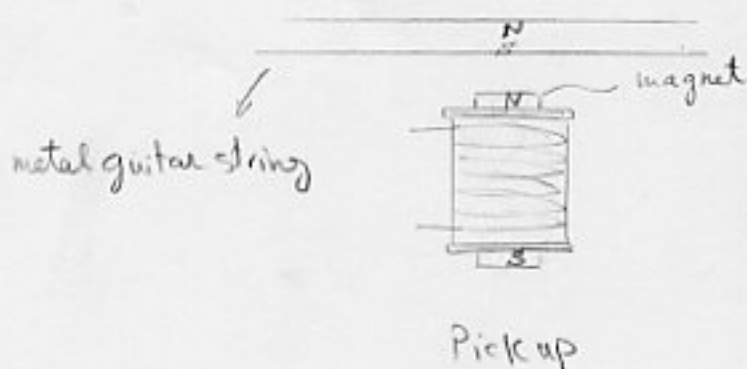
Lenz's Law and Energy Conservation:

What would happen if Lenz's law were turned the other way around, that is, if the induced current acted, to aid the change that produced it.

This would be in contradiction with energy conservation and can not happen.

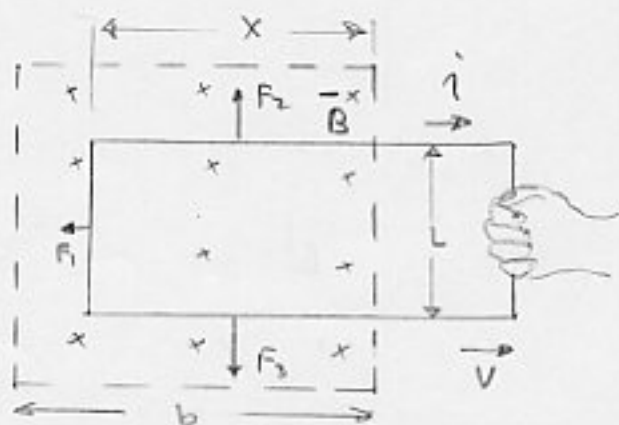
Work done on the magnet = thermal energy + electromagnetic radiation
 (to compensate resisting) force

Ex



32-5 Induction: A quantitative study;

Change in Φ_B may occur due to the motion of the loop while $\vec{B} = \text{const}$.



Rate of Doing Work:

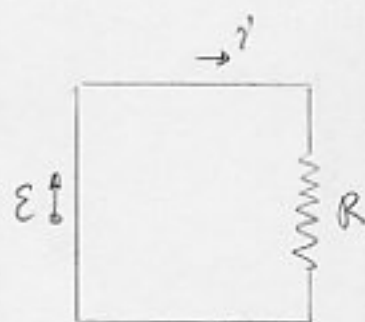
To move the loop a force F must be applied to the loop by hand (which is in opposite dir. of the force acted to the loop but the same magnitude to give a const. velocity v).

$$P = Fv$$

$$\Phi = BLx$$

$$\mathcal{E} = \frac{dq}{dt} = \frac{d}{dt}(BLx) = BL \frac{dx}{dt} = BLv$$

To find i we cannot apply the loop rule, because we can not define a potential for an induced emf.



But we can use energy method;

$$dw = \mathcal{E} dq = \mathcal{E} i dt$$

$$\mathcal{E} i dt = i^2 R dt \rightarrow \mathcal{E} = iR$$

$$i = \frac{\mathcal{E}}{R} = \frac{BLv}{R}$$

Also

$$\vec{F} = i \vec{L} \times \vec{B}$$

The contributions from \vec{F}_2 and \vec{F}_3 cancel each other.

B is perpendicular to \vec{L}

$$\vec{F} = -\vec{F}_1$$

$$F = F_1 = iLBsq_0 = iLB$$

$$F = \frac{B^2 L^2 v}{R}$$

B, L, R are const.

\rightarrow If $F = \text{const} \rightarrow v = \text{const}.$

$$P = Fv = \frac{B^2 L^2 v^2}{R}$$

The Thermal Energy,

$$P = Ri^2 = R \left(\frac{BLv}{R} \right)^2 = \frac{B^2 L^2 v^2}{R} \quad \text{thermal energy rate}$$

which is exactly equal to the rate of work done by \vec{F} ($P = Fv$).

Ex.

Suppose the loop in Fig (P196) has $N=185$ Turns Copper wire.

$$L = 13 \text{ cm}, B = 1.5 \text{ T}, R = 6.2 \Omega, v = 18 \text{ cm/s}$$

a) $\mathcal{E} = ?$ $\mathcal{E} = NBLv = (185 \text{ turns})(1.5 \text{ T})(0.13 \text{ m})(0.18 \text{ m/s})$

$$\mathcal{E} = 2.98 \text{ V}$$

b) $i = ?$ (induced current) $i = \frac{\mathcal{E}}{R} = \frac{2.98 \text{ V}}{6.2 \Omega} = 0.48 \text{ A}$

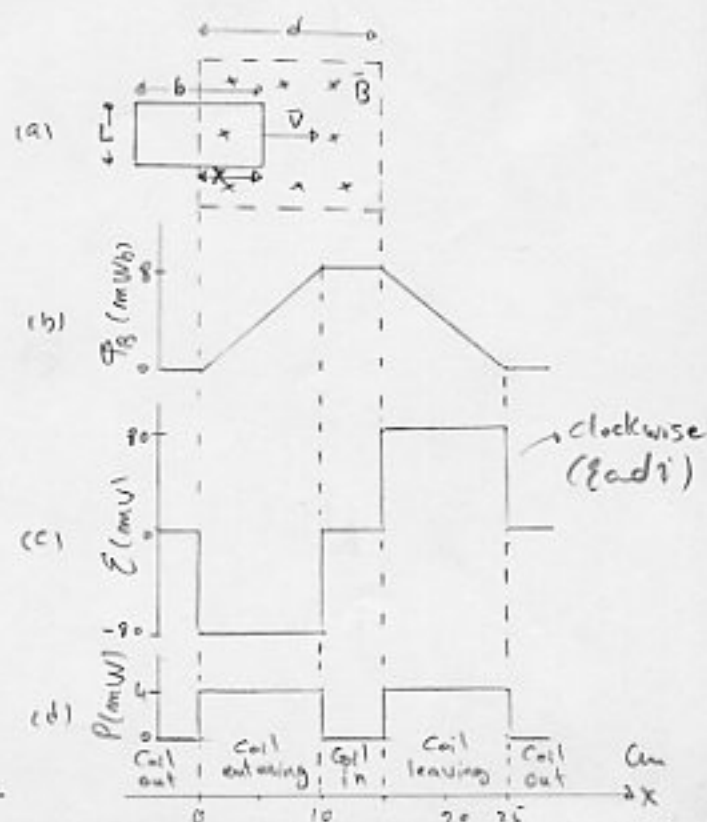
c) $F = ?$ (the applied force)

$$F = NiLB = (185 \text{ turns})(0.48 \text{ A})(0.13 \text{ m})(1.5 \text{ T}) = 8.0 \text{ N}$$

d) $P = ?$ $P = Fv = (8.0 \text{ N})(0.18 \text{ m/s}) = 1.4 \text{ W}$

Ex.

Fig. shows a rectangular conducting loop of resistance R , width L , and length b being pulled at const. speed v through a region of width d in which uniform \vec{B} .



a) plot $\Phi_B(x)$,

$$L = 40 \text{ mm}, b = 10 \text{ cm}, d = 15 \text{ cm}$$

$$R = 1.6 \Omega, B = 2.0 \text{ T}, v = 1.0 \text{ m/s}$$

$$\Phi_{\min} = 0 \quad \Phi_{\max} = BLb = 8 \text{ mWb}$$

$$\Phi = BLx \quad \text{entering}$$

$$\Phi = BL[b - (x - d)] \quad \text{leaving}$$

$$b) \text{ Plot } \mathcal{E}, \quad \mathcal{E} = -\frac{d\phi_B}{dt} = -\frac{d\phi_B}{dx} \frac{dx}{dt} = -\frac{d\phi_B}{dx} v$$

$$c) \text{ Plot } P, \quad P = i^2 R = \frac{\mathcal{E}^2}{R} \quad \text{also} \quad P = \frac{B^2 L^2 v^2}{R}$$

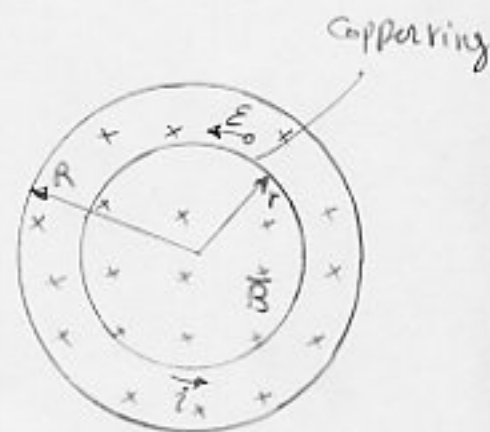
32-6 Induced Electric Fields

Fig. 1: \vec{B} is increasing at a steady rate.

→ \mathcal{E} and i are induced.

if there is induced i → there should be induced \vec{E} within the loop

leading to a force $q_0 \vec{E}$ on a test charge



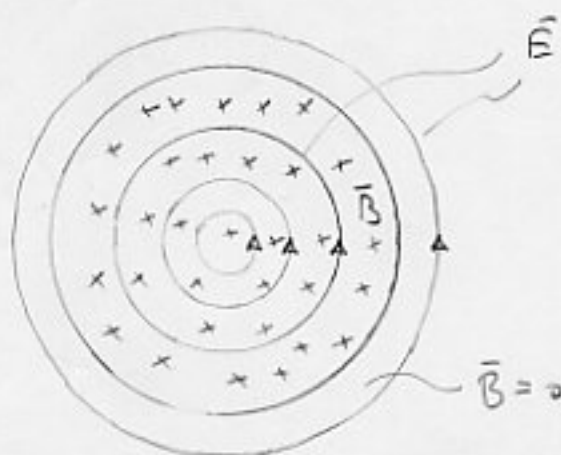
(a)

$$\vec{B} = \alpha t \hat{k} \quad \alpha = \text{const} > 0$$

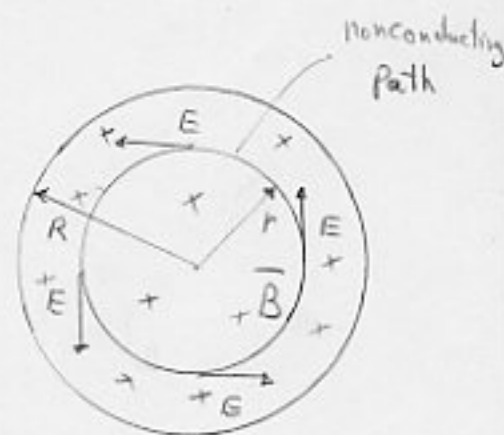
(increasing)

Changing \vec{B} → produces \vec{E}

\vec{E} is produced even if there is no conducting ring.



$$\vec{B} = \alpha t \hat{k} \quad \alpha = \text{const} > 0$$



(b)

$$\vec{B} = \alpha t \hat{k} \quad \alpha = \text{const} > 0$$

A Reformulation of Faraday's Law:

$$W = \mathcal{E}q_0 \quad \text{the work done on } q_0 \text{ in one revolution}$$

on the other hand $W = \int \vec{F} \cdot d\vec{s} = (q_0 \vec{E}) (2\pi r)$

$$\rightarrow \mathcal{E} = E 2\pi r$$

In general case $\mathcal{E} = \oint \vec{E} \cdot d\vec{s}$

New def. for induced \mathcal{E} :

Old def: The work done per unit charge in maintaining current in a circuit owing to a changing Φ_B .

or: The work done per unit charge on a test charge that moves around a closed path in a changing Φ_B .

New def: An induced \mathcal{E} is the sum - via integration - of quantities $\vec{E} \cdot d\vec{s}$ around a closed path, where \vec{E} is the electric field induced by a changing Φ_B and $d\vec{s}$ is a differential length vector along the path.

$$\mathcal{E} = - \frac{d\Phi_B}{dt} \rightarrow \oint \vec{E} \cdot d\vec{s} = - \frac{d\Phi_B}{dt} \text{ (Faraday's law)}$$

$$\mathcal{E} = \oint \vec{E} \cdot d\vec{s}$$

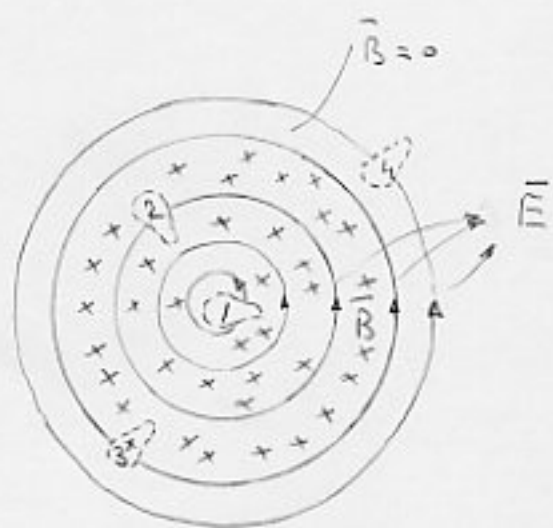
$$\mathcal{E} = \oint \vec{E} \cdot d\vec{s} = - \frac{d\Phi_B}{dt}$$

$$\oint_1 \vec{E} \cdot d\vec{s} = \oint_2 \vec{E} \cdot d\vec{s}$$

$$\text{(because } \frac{d\Phi_1}{dt} = \frac{d\Phi_2}{dt} \text{)}$$

$$\oint_3 \vec{E} \cdot d\vec{s} < \oint_1 \vec{E} \cdot d\vec{s}$$

$$\oint_4 \vec{E} \cdot d\vec{s} = 0 \quad \left(\frac{d\Phi_B}{dt} = 0 \right)$$



(d)

$$\vec{B} = \alpha t \hat{k} \quad \alpha = \text{const} > 0$$

A New look at Electric Potential:

Induced \vec{E} is not produced by static charges, but by changing Φ_B .

The important difference;

- { \vec{E} produced by static charge start from positive charge and end on negative charges.
- { Induced \vec{E} form a closed loop.

In a more formal sense;

Electric potential has meaning only for electric fields that are produced by static charges; it has no meaning for electric fields that are produced by induction.

Explanation:

Consider a test charge that makes a single journey around a single path (Fig. P 200) -

During this single round it has experienced an emf \mathcal{E} of say $\mathcal{E} = C$ volt

→ Its potential should have increased by this amount

This is impossible, however, because otherwise a single point in space would have two different values of V .

→ V has no meaning for \vec{E} induced by changing \mathcal{P}_B .

More formal look;

$$V_f - V_i = \frac{W_{if}}{q_0} = - \int_i^f \vec{E} \cdot d\vec{s}$$

$$\text{if } i=f \rightarrow \oint \vec{E} \cdot d\vec{s} = 0$$

$$\text{But there is a changing } \mathcal{P}_B \rightarrow \oint \vec{E} \cdot d\vec{s} = - \frac{d\mathcal{P}_B}{dt} \rightarrow V \text{ has no meaning}$$

Ex. In (Fig. b, P200), $R = 8.5 \text{ cm}$, $\frac{dB}{dt} = 0.13 \text{ T/s}$

a) Induced $\vec{E} = ?$ when $r = 5.2 \text{ cm}$

$$\oint \vec{E} \cdot d\vec{s} = (E)(2\pi r) = -\frac{d\Phi_B}{dt}$$

$$r < R, \quad \Phi_B = B(\pi r^2)$$

$$(E)(2\pi r) = -(\pi r^2) \frac{dB}{dt} \quad E = \frac{1}{2} \left(\frac{dB}{dt} \right) r$$

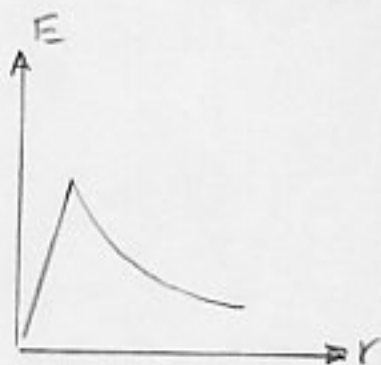
$$E = \left(\frac{1}{2} \right) (0.13 \text{ T/s}) (5.2 \times 10^{-2} \text{ m}) = 0.0034 \text{ V/m}$$

b) Induced $\vec{E} = ?$ at $r = 12.5 \text{ cm}$

$$r > R, \quad \Phi_B = B(\pi R^2)$$

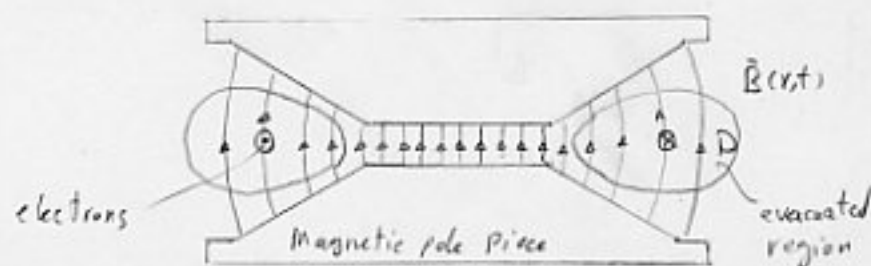
$$(E)(2\pi r) = -\frac{d\Phi_B}{dt} = -(\pi R^2) \frac{dB}{dt} \quad E = \frac{1}{2} \left(\frac{dB}{dt} \right) \frac{R^2}{r}$$

$$E = \frac{\left(\frac{1}{2} \right) (0.13 \text{ T/s}) (8.5 \times 10^{-2} \text{ m})^2}{12.5 \times 10^{-2} \text{ m}} = 3.8 \times 10^{-3} \text{ V/m}$$



32-7 The Betatron

The device accelerates electrons by allowing them to be acted on by induced \vec{E} .



Time varying $\bar{B}(r, t)$ has several functions:

- 1- It guides the electrons in a circular path
- 2- The changing T_B generates an induced \bar{E} accelerating the electrons in this path.
- 3- It keeps the radius of the electron orbit essentially constant during the acceleration process.
- 4- It injects the electrons into the orbit initially and extracts them from the orbit after they have reached their full energy.
- 5- It provides a restoring force that resists any tendency for the electrons to stray away from their orbit, either vertically or radially.

These are done by proper shaping and control of the $\bar{B}(r, t)$

B_{orb} at orbit position serves to guide the electrons in their orbit.

The field in the area enclosed by the orbit, with the average value B_{av} ($= 2 B_{orb}$) contributes to the central flux Φ_B .

The time variation of this central flux induce \bar{E} , accelerating the electrons

Ex.

In a 100 MeV Betatron, $R = 84 \text{ cm}$.

B in the region enclosed by the orbit rises and falls with the frequency $f = 60 \text{ Hz}$ from zero to a maximum average of $B_{av, \max} = 0.80 \text{ T}$.

An electron is fully accelerated in $\frac{1}{4}$ of a magnetic-field period (4.2 ms) ($4.2 \times 10^{-3} \approx \frac{1}{4} \frac{1}{60}$)

a) How much energy does the electron gain in one average trip around its orbit in this changing Φ_B ?

$$\Phi_{\max} = (B_{av, \max})(2\pi R) = (0.80 \text{ T})(\pi 10.84 \text{ m}^2) = 1.8 \text{ Wb}$$

$$\left(\frac{d\Phi_B}{dt}\right)_{av} = \frac{1.8 \text{ Wb}}{4.2 \times 10^{-3} \text{ s}} = 430 \text{ Wb/s}$$

$$\text{Since } \mathcal{E} = -\frac{d\Phi_B}{dt} \rightarrow \mathcal{E}_{av} = 430 \text{ Wb/s} \quad (\text{Volts}) \quad (430 \times 1.6 \times 10^{-19} \text{ J})$$

→ The energy of the electron increase by an average of 430 eV

Full final energy = 100 MeV

$$\frac{100 \times 10^6 \text{ eV}}{430} = 230,000 \text{ revolutions} \rightarrow 230,000(2\pi R) = 1200 \text{ km}$$

b) $\bar{V}_{av} = ?$ average speed during its acceleration

$$\bar{V} = \frac{1200 \times 10^3 \text{ m}}{4.2 \times 10^{-3} \text{ s}} = 2.86 \times 10^8 \text{ m/s} \quad (95\%)$$

(An actual value $\bar{V} = 99.9987\% \text{ c}$ considering relativity)