

Chapter 3

Interpolation and Polynomial Approx.:

Def.: Fitting a func. to a given data is called interpolation, (the func. satisfies exactly at all given data) -

Most useful func. mapping;

(set of real numbers) $\xrightarrow{\text{into}}$ (itself)

are algebraic polynomials;

$$P_n(x) = a_n x^n + a_{n-1} x^{n-1} + \dots + a_1 x + a_0$$

Their derivatives and integrals can be taken easily.

Theo. 3.1 (Weierstrass Approx. Theo.)

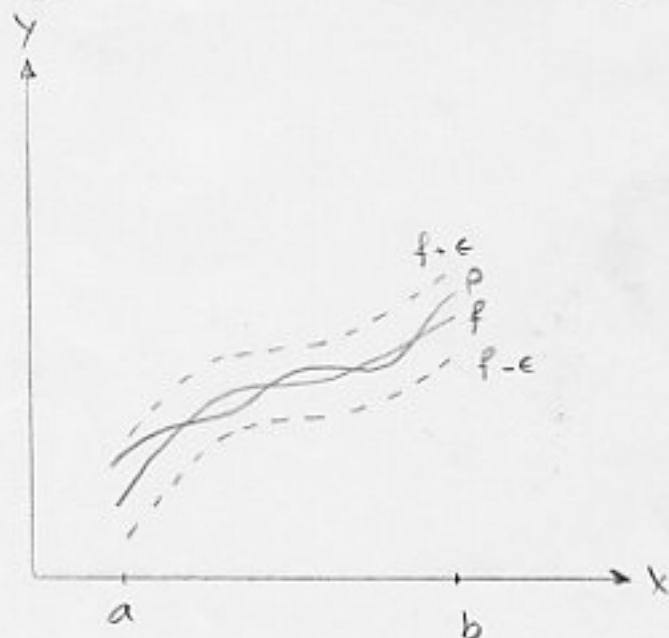
If f is defined and continuous on $[a, b]$ and $\epsilon > 0$ is given

then $\exists P(x)$ defined on $[a, b]$

with the property

$$|f(x) - P(x)| < \epsilon$$

$$\forall x \in [a, b]$$



($P(x)$: Polynomial)

3.1 The Taylor polynomials:

We consider the prob. of finding a polynomial of a specific deg. that is close to a given func. at a point x_0 , (not all points) -

P agrees with f at x_0 precisely when $P(x_0) = f(x_0)$

P has the same direction as f at $(x_0, f(x_0))$ if $P'(x_0) = f'(x_0)$

P_n of deg. n best approximates f near x_0 if:

$$P''(x_0) = f''(x_0), \quad P'''(x_0) = f'''(x_0) \dots$$

This is precisely the cond. satisfied by n th Taylor polynomial for f at x_0 .

$$P_n(x) = f(x_0) + f'(x_0)(x-x_0) + f''(x_0) \frac{(x-x_0)^2}{2!} + \dots + f^{(n)}(x_0) \frac{(x-x_0)^n}{n!}$$

$$f(x) - P_n(x) = R_n(x) = \frac{f^{(n+1)}(\xi)}{(n+1)!} (x-x_0)^{n+1}$$

Ex.

- Calculate the third Taylor polynomial about $x_0 = 0$ for $f(x) = (1+x)^{1/2}$
- Use the polynomial in part (a) to approximate $\sqrt{1.1}$ and find a bound for the error involved.
- Use the polynomial in part (a) to approximate $\int_0^{0.1} (1+x)^{1/2} dx$ and find a bound for the error of this approx.

$$f(x) = (1+x)^{1/2} \quad f(0) = 1$$

$$f'(x) = \frac{1}{2}(1+x)^{-1/2} \quad f'(0) = \frac{1}{2}$$

$$f''(x) = -\frac{1}{4}(1+x)^{-3/2} \quad f''(0) = -\frac{1}{4}$$

$$f'''(x) = \frac{3}{8}(1+x)^{-5/2} \quad f'''(0) = \frac{3}{2}$$

$$f^{(iv)}(x) = -\frac{15}{16}(1+x)^{-7/2} \quad f^{(iv)}(\xi) = -\frac{15}{16}(1+\xi)^{-7/2} \quad \xi: \text{between } x_0=0 \text{ and } x$$

$$a) \quad P_3(x) = f(0) + f'(0)x + \frac{f''(0)}{2!}x^2 + \frac{f'''(0)}{3!}x^3 = 1 + \frac{1}{2}x - \frac{1}{8}x^2 + \frac{1}{16}x^3$$

$$b) \quad \sqrt{1.1} = (1+0.1)^{1/2} = f(0.1) = P_3(0.1) = 1 + \frac{1}{2}(0.1) - \frac{1}{8}(0.1)^2 + \frac{1}{16}(0.1)^3 = 1.0488125$$

$$|R_3(0.1)| = \frac{|-\frac{15}{16}(1+\xi)^{-7/2}|}{4!} (0.1)^4 \leq \frac{15}{(16)(24)} (0.1)^4 \max_{\xi \in [0, 0.1]} (1+\xi)^{-7/2}$$

$$= \frac{0.0005}{128} (1) \leq 3.91 \times 10^{-6}$$

True value is 1.0488088 \rightarrow the actual error $\approx 3.7 \times 10^{-6}$

$$c) \quad \int_0^{0.1} (1+x)^{1/2} dx \approx \int_0^{0.1} P_3(x) dx = \int_0^{0.1} \left(1 + \frac{x}{2} - \frac{x^2}{8} + \frac{x^3}{16}\right) dx$$

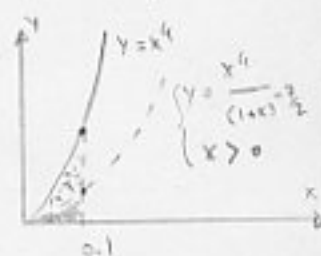
$$= \left[x + \frac{x^2}{4} - \frac{x^3}{24} + \frac{x^4}{64} \right]_0^{0.1} = 0.1024598958$$

$$|\int_0^{0.1} R_3(x) dx| = \frac{15}{(16)(4!)} \int_0^{0.1} (1+\xi)^{-7/2} x^4 dx$$

$$\leq \frac{5}{128} \int_0^{0.1} x^4 dx = \frac{5}{128} \cdot \left[\frac{x^5}{5} \right]_0^{0.1} \leq 7.82 \times 10^{-8}$$

Since $\int_0^{0.1} R_3(x) dx = \text{negative}$

Remark:



$$\int_0^{0.1} \frac{x^4}{(1+x)^{7/2}} dx < \int_0^{0.1} x^4 dx$$

for $x > 0$

$$\rightarrow \int_0^{0.1} P_3(x) dx - \left| \int_0^{0.1} R_3(x) dx \right| \leq \int_0^{0.1} (1+x)^{1/2} dx \leq \int_0^{0.1} P_3(x) dx$$

$$0.1024598176 \leq \int_0^{0.1} (1+x)^{1/2} dx \leq 0.1024598758$$

The actual value of $\int_0^{0.1} (1+x)^{1/2} dx = 0.102459822$

$$\rightarrow \text{True error} = 7.4 \times 10^{-8}$$

Ex.

$$f(x) = (1+x)^{1/2} \quad \text{and } P_3(x), \quad x_0 = 0$$

x	0.1	0.5	1	2	10
$P_3(x)$	1.048813	1.2266	1.438	2.00	56.00
$f(x)$	1.048809	1.2247	1.414	1.73	3.32
$ P_3(x) - f(x) $	0.000004	0.0019	0.024	0.27	52.68

\uparrow
 $x_0 = 0 \xrightarrow{\text{close}} 0.1$

\uparrow
 large departure

$$x_0 = 0 \ll 10$$

Ex. (Extreme Example)

$$f(x) = \frac{1}{x} \quad x_0 = 1 \quad \text{to approximate } f(3) = \frac{1}{3}$$

Sol.

$$f^{(n)}(x) = (-1)^n n! x^{-n-1}$$

$$P_n(x) = \sum_{k=0}^n \frac{f^{(k)}(1)}{k!} (x-1)^k = \sum_{k=0}^n (-1)^k (x-1)^k$$

n	0	1	2	3	4	5	6	7
$P_n(3)$	1	-1	3	-5	11	-21	43	-81

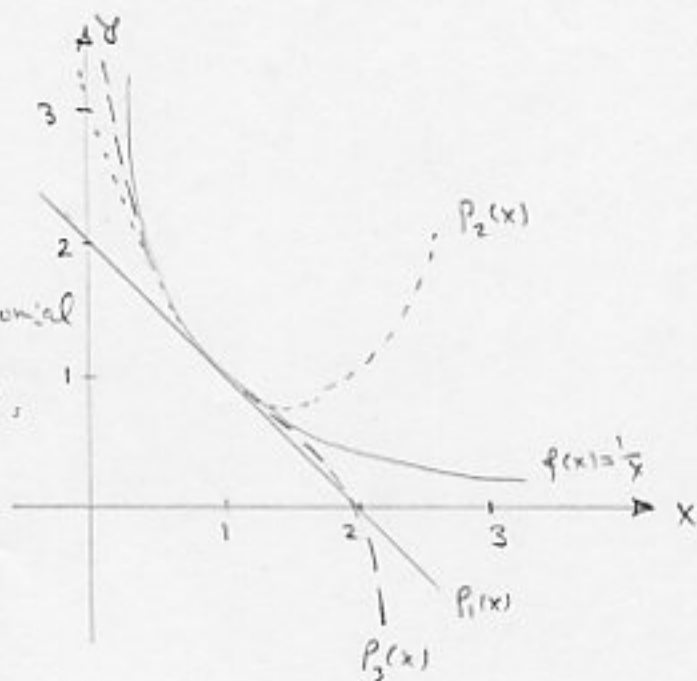
$$f(3) = 0.3333\bar{3}$$

$$P_n(x) = \frac{(-1)^{n+1} (x-1)^{n+1}}{\xi^{n+2}}$$

ξ : between 1 and x

Since information in Taylor polynomial is concentrated at a single point x_0 , this kind of difficulties arise in this method.

This method is useful when the approximation is needed at points very close to x_0 .



3.2 Interpolation and the Lagrange polynomial:

Determination of polynomial of deg. $n=1$ that passes through (x_0, y_0) and (x_1, y_1) :

$$\rightarrow \begin{cases} y_0 = f(x_0) \\ y_1 = f(x_1) \end{cases} \quad \left(\begin{array}{l} \text{approximating func. } f \\ \text{which satisfies these ends.} \end{array} \right)$$

Consider linear polynomial:

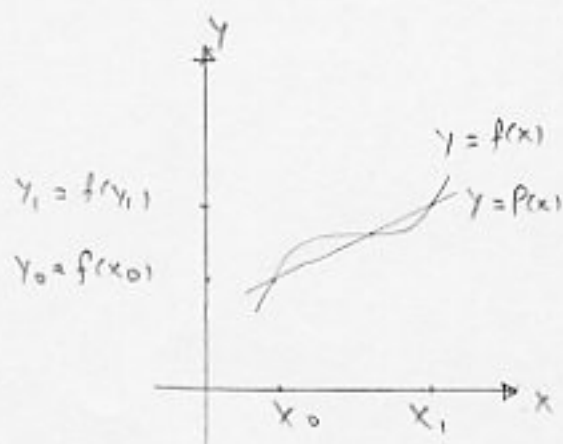
$$P(x) = \frac{(x-x_1)}{(x_0-x_1)} y_0 + \frac{(x-x_0)}{(x_1-x_0)} y_1$$

$$x = x_0 \rightarrow P(x_0) = 1 \cdot y_0 + 0 \cdot y_1 = y_0 = f(x_0)$$

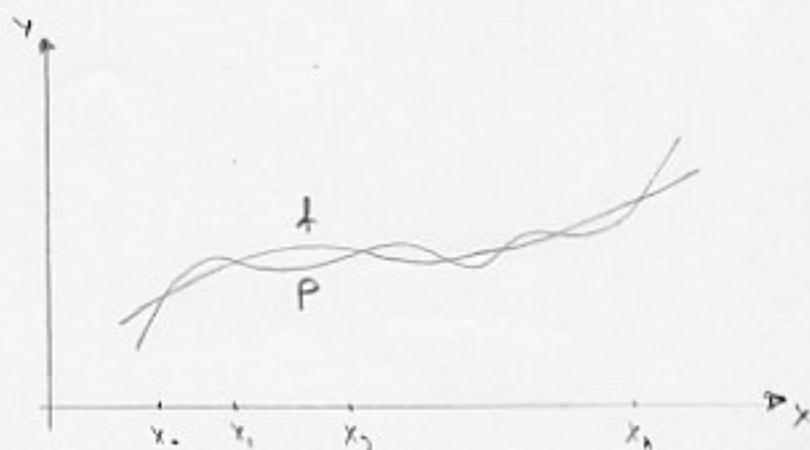
$$x = x_1 \rightarrow P(x_1) = 0 \cdot y_0 + 1 \cdot y_1 = y_1 = f(x_1)$$

Generalization:

Construction of a polynomial
of deg. at most n that passes
through $n+1$ points, $(x_0, f(x_0))$
 $(x_1, f(x_1)) \dots (x_n, f(x_n))$ (Fig.)



The linear polynomial
passing through:
 $\begin{cases} (x_0, f(x_0)) \\ (x_1, f(x_1)) \end{cases}$



is constructed by using
the quotients:

$$L_0(x) = \frac{(x-x_1)}{(x_0-x_1)} \quad \text{and} \quad L_1(x) = \frac{(x-x_0)}{(x_1-x_0)}$$

$$x = x_0 \rightarrow L_0(x_0) = 1 \quad \text{and} \quad L_1(x_0) = 0$$

$$x = x_1 \rightarrow L_1(x_1) = 1 \quad \text{and} \quad L_0(x_1) = 0$$

For the general case; we have to construct $L_{n,k}(x)$ with
the property;

$$L_{n,k}(x_i) = 0 \quad i \neq k$$

$$L_{n,k}(x_k) = 1$$

$$L_{n,k}(x_i) = \frac{A}{B}$$

To satisfy $L_{n,k}(x_i) = 0$ for $i \neq k$

A must contain; $(x-x_0)(x-x_1) \dots (x-x_{k-1})(x-x_{k+1}) \dots (x-x_n)$

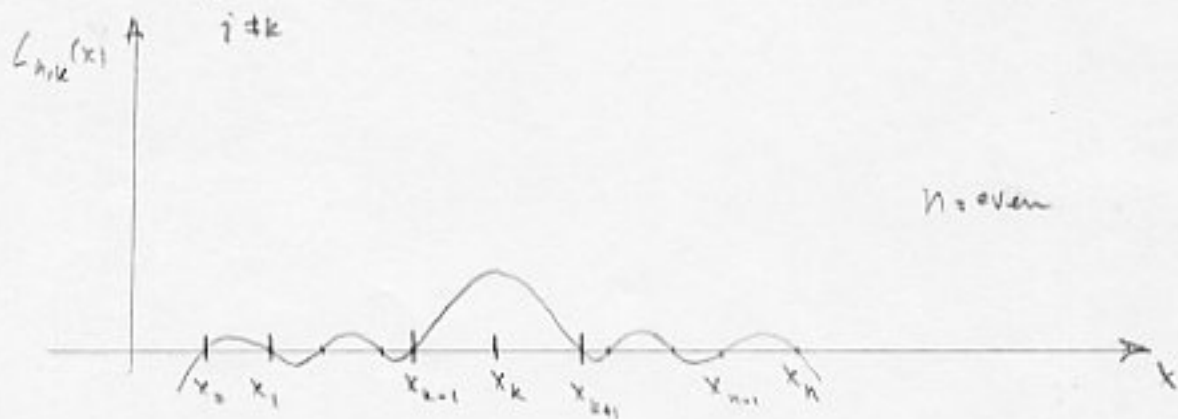
To satisfy $L_{n,k}(x_k) = 1$

B must be equal $\dots = \dots = \dots = \dots = \dots$

when $x = x_k$

Thus \rightarrow
$$L_{n,k}(x) = \frac{(x-x_0) \dots (x-x_{k-1})(x-x_{k+1}) \dots (x-x_n)}{(x_k-x_0) \dots (x_k-x_{k-1})(x_k-x_{k+1}) \dots (x_k-x_n)}$$

$$L_{n,k}(x) = \prod_{\substack{i=0 \\ i \neq k}}^n \frac{(x-x_i)}{(x_k-x_i)}$$



Theo. 3.2

If x_0, x_1, \dots, x_n are $(n+1)$ distinct numbers and f is a func. whose values are given at these numbers, then there exists a unique polynomial P of deg. at most n with the property that

$$f(x_k) = P(x_k) \quad \text{for each } k = 0, 1, \dots, n$$

This polynomial is given by

$$P(x) = f(x_0) L_{n,0}(x) + \dots + f(x_n) L_{n,n}(x)$$

$$= \sum_{k=0}^n f(x_k) L_{n,k}(x)$$

where $L_{n,k}(x) = \prod_{\substack{i=0 \\ i \neq k}}^n \frac{(x-x_i)}{(x_k-x_i)}$ $k=0, 1, \dots, n$

Ex.

Using the numbers, or nodes $x_0=2, x_1=2.5, x_2=4$, find the second interpolating polynomial $f(x) = \frac{1}{x}$.

Sol.

$$L_0(x) = \frac{(x-2.5)(x-4)}{(2-2.5)(2-4)} = (x-6.5)x + 10$$

$$L_1(x) = \frac{(x-2)(x-4)}{(2.5-2)(2.5-4)} = \frac{(-4x+24)x-32}{3}$$

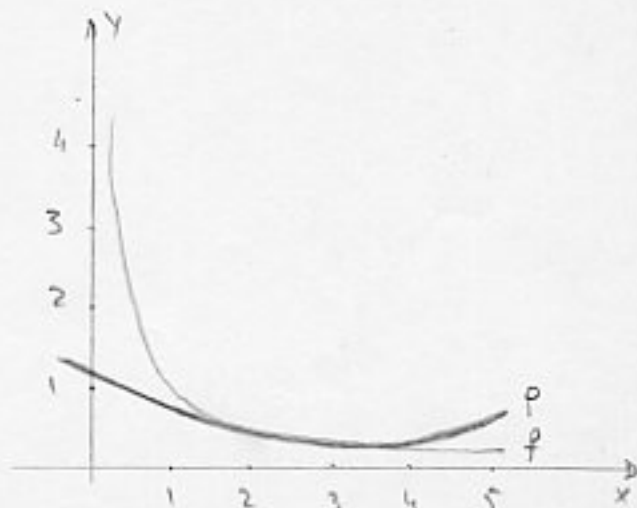
$$L_2(x) = \frac{(x-2)(x-2.5)}{(4-2)(4-2.5)} = \frac{(x-4.5)x+5}{3}$$

$$f(x_0) = f(2) = 0.5 \quad f(x_1) = f(2.5) = 0.4 \quad f(x_2) = f(4) = 0.25$$

$$P(x) = \sum_{k=0}^2 f(x_k) L_k(x) = 0.5 \{ (x-6.5)x + 10 \} + 0.4 \left\{ \frac{(-4x+24)x-32}{3} \right\}$$

$$+ 0.25 \left\{ \frac{(x-4.5)x+5}{3} \right\} = (0.05x - 0.425)x + 1.15$$

An approx. to $f(3) = P(3) = 0.325$



Theo. 3.3

If x_0, x_1, \dots, x_n are distinct numbers in the interval $[a, b]$ and

$f \in C^{n+1}[a, b] \xrightarrow{\text{then}} \exists$ a number $\xi(x)$ in (a, b) , $\forall x \in [a, b]$

with

$$f(x) = P(x) + \frac{f^{(n+1)}(\xi(x))}{(n+1)!} \prod_{i=0}^n (x-x_i)$$

where P is the interpolating polynomial

$$P(x) = \sum_{k=0}^n f(x_k) L_{n,k}(x)$$

Compare the error formula in this theorem with that one in Taylor polynomial:

$$\left\{ \begin{array}{l} \frac{f^{(n+1)}(\xi(x))}{(n+1)!} (x-x_0)^{n+1} \\ \frac{f^{(n+1)}(\xi(x))}{(n+1)!} \prod_{i=0}^n (x-x_i) \end{array} \right.$$

for Taylor polynomial

" Lagrange "

The Taylor polynomial of deg. n about x_0 concentrates all the known information at x_0 .

The Lagrange polynomial of deg. n uses information at the distinct numbers x_0, x_1, \dots, x_n .

Ex.

Assume a table is to be prepared for the func. $f(x) = e^x$,
 $0 \leq x \leq 1$ (with the step size h) and the number of decimal
places d .

- a) If $d \geq 6$, what should h be for linear interpolation (Lagrange
polynomial of deg. 1) to give an absolute error at most 10^{-6} ?
- b) How does the situation in part (a) change if $d < 6$?

Sol.

$$\text{let } x \in [0, 1] \quad \text{and } x_j \leq x \leq x_{j+1} \quad \left(\begin{array}{l} x_j = 0 + jh \\ x_{j+1} = 0 + (j+1)h \end{array} \right)$$

Error in linear interpolation:

$$\begin{aligned} |f(x) - P(x)| &= \left| \frac{f^{(2)}(\xi(x))}{2!} (x-x_j)(x-x_{j+1}) \right| = \frac{|f^{(2)}(\xi)|}{2} |(x-x_j)(x-x_{j+1})| \\ &= \frac{|f^{(2)}(\xi(x))|}{2!} |(x-jh)(x-(j+1)h)| \end{aligned}$$

Hence

$$|f(x) - P(x)| \leq \frac{1}{2} \max_{\xi \in [0, 1]} |f^{(2)}(\xi)| \cdot \max_{x_j \leq x \leq x_{j+1}} |(x-jh)(x-(j+1)h)|$$

$$= \frac{1}{2} \max_{\xi \in [0, 1]} e^{\xi} \cdot \max_{x_j \leq x \leq x_{j+1}} |(x-jh)(x-(j+1)h)|$$

$$\leq \frac{1}{2} e \cdot \max_{x_j \leq x \leq x_{j+1}} |(x-jh)(x-(j+1)h)|$$

Taking : $g(x) \equiv (x-jh)(x-(j+1)h)$

Max $|g(x)| = |g(j+\frac{1}{2}h)| = \frac{h^2}{4}$ ($g'(x) = 0 \rightarrow \text{max}$)
 $\rightarrow x = j+\frac{1}{2}$

\rightarrow The error in linear interpolation is bounded by

$$|f(x) - P(x)| \leq \frac{eh^2}{8}$$

$$\frac{eh^2}{8} \leq 10^{-6} \quad \rightarrow h < 1.72 \times 10^{-3}$$

$\rightarrow h = 0.001$ is logical choice

b) If the tables are accurate only to the fifth decimal place, it is impossible to obtain accurate values to the sixth place interpolation.

Ex

The following table lists the values of the Bessel func. of the first kind of order zero at various points. Compare the approximation of $f(1.5)$ obtained by various Lagrange Polynomials.

Sol.

Since 1.5 is between 1.3 and 1.6,

The linear polynomial will use $\begin{cases} x_0 = 1.3 \\ x_1 = 1.6 \end{cases}$

<u>x</u>	<u>f(x)</u>
1.0	0.7651977
1.3	0.6200860
1.6	0.4554022
1.9	0.2818186
2.2	0.1103623

$$P_1(1.5) = \frac{(1.5-1.6)}{(1.3-1.6)} (0.6200860) + \frac{(1.5-1.3)}{(1.6-1.3)} (0.4554022) = 0.5102968$$

Two polynomials of deg. two could reasonably be used:

$$i) \begin{cases} x_0 = 1.3 \\ x_1 = 1.6 \\ x_2 = 1.9 \end{cases} \quad P_2(1.5) = \frac{(1.5-1.6)(1.5-1.9)}{(1.3-1.6)(1.3-1.9)} (0.6200860) + \frac{(1.5-1.3)(1.5-1.9)}{(1.6-1.3)(1.6-1.9)} (0.4554022) + \frac{(1.5-1.3)(1.5-1.6)}{(1.9-1.3)(1.9-1.6)} (0.2818186) = 0.5112857$$

$$ii) \begin{cases} x_0 = 1.0 \\ x_1 = 1.3 \\ x_2 = 1.6 \end{cases} \quad \rightarrow \hat{P}_2(1.5) = 0.5124715$$

In the third deg. case there are also two choices:

$$i) \begin{cases} x_0 = 1.3 \\ x_1 = 1.6 \\ x_2 = 1.9 \\ x_3 = 2.2 \end{cases} \quad \rightarrow P_3(1.5) = 0.5118302$$

$$ii) \begin{cases} x_0 = 1.0 \\ x_1 = 1.3 \\ x_2 = 1.6 \\ x_3 = 1.9 \end{cases} \quad \rightarrow \hat{P}_3(1.5) = 0.5118127$$

The fourth deg. Lagrange polynomial:

$$\begin{cases} x_0 = 1.0 \\ x_1 = 1.3 \\ x_2 = 1.6 \\ x_3 = 1.9 \\ x_4 = 2.2 \end{cases} \quad \rightarrow P_4(1.5) = 0.5118200$$

$$f(1.5) = 0.5118277 \quad \text{actual value}$$

$$|P_1(1.5) - f(1.5)| \approx 1.53 \times 10^{-3}$$

$$|P_2(1.5) - f(1.5)| \approx 5.42 \times 10^{-4}$$

$$|\hat{P}_2(1.5) - f(1.5)| \approx 6.66 \times 10^{-4}$$

$$|P_3(1.5) - f(1.5)| \approx 2.5 \times 10^{-6}$$

$$|\hat{P}_3(1.5) - f(1.5)| \approx 1.50 \times 10^{-5}$$

$$|P_4(1.5) - f(1.5)| \approx 7.7 \times 10^{-6}$$

← most accurate

However with no knowledge of the actual value of $f(1.5)$, P_4 would be accepted as the best approx. -

Note that the error (or remainder term) can not be applied here, since no knowledge of the fourth derivative of f is available.

Unfortunately, this is generally the case.

3.3 Iterated Interpolation.

The deg. of the polynomial needed for the desired accuracy, using the method in 3.2, is generally not known until computations are determined (Comparing the result of P_n with P_{n-1}). (Since error term is difficult to work with)

Another difficulty;

One can not get information for P_n from P_{n-1} , and each one must be calculated separately.

Def. 3.4

Let f be a func. defined at x_0, x_1, \dots, x_n and suppose that m_1, m_2, \dots, m_k are k distinct integers with $0 \leq m_i \leq n \quad \forall i$.

The Lagrange polynomial that agrees with f at the k points $x_{m_1}, x_{m_2}, \dots, x_{m_k}$ is denoted P_{m_1, m_2, \dots, m_k} .

Ex. If $x_0=1, x_1=2, x_2=3, x_3=4, x_4=6$ and $f(x)=x^3$ then $P_{1,2,4}$ is the polynomial that agrees with f at $x_1=2, x_2=3$, and $x_4=6$;

$$P_{1,2,4}(x) = \frac{(x-3)(x-6)}{(2-3)(2-6)} (8) + \frac{(x-2)(x-6)}{(3-2)(3-6)} (27) + \frac{(x-2)(x-3)}{(6-2)(6-3)} (216)$$

Theo. 3.5

Let f be defined at x_0, x_1, \dots, x_k and x_j, x_i be two distinct numbers in this set. If

$$P(x) = \frac{(x-x_j) P_{0,1,\dots,j-1,j+1,\dots,k}(x) - (x-x_i) P_{0,1,\dots,i-1,i+1,\dots,k}(x)}{(x_i-x_j)}$$

then P is the k th Lagrange polynomial that interpolates f at the $k+1$ points x_0, x_1, \dots, x_k .

Ex.

We obtained the values of various Lagrange polynomials at $x=1.5$ using the following table in the last example.

Now we calculate the approx. of $f(1.5)$ using Theo. 3.5.

$$\text{If } \begin{cases} x_0 = 1.0 \\ x_1 = 1.3 \\ x_2 = 1.6 \\ x_3 = 1.9 \\ x_4 = 2.2 \end{cases} \rightarrow \begin{cases} f(1.0) = P_0 \\ f(1.3) = P_1 \\ f(1.6) = P_2 \\ f(1.9) = P_3 \\ f(2.2) = P_4 \end{cases} \quad \begin{matrix} (\text{deg. zero}) \\ (\text{consts.}) \end{matrix}$$

x	$f(x)$
1.0	0.7651977
1.3	0.6200860
1.6	0.4554020
1.9	0.2818186
2.2	0.1103623

$$P_{0,1}(1.5) = \frac{(1.5-1.0)P_1 - (1.5-1.3)P_0}{(1.3-1.0)} = \frac{0.5(0.6200860) - 0.2(0.7651977)}{0.3} = 0.5233449$$

$$P_{1,2}(1.5) = 0.5102968$$

$$P_{2,3}(1.5) = 0.5132634$$

$$P_{3,4}(1.5) = 0.5104270$$

These are first deg. polynomials.

$P_{1,2}$ is expected to be the best approximation, since $x_1=1.3 < 1.5 < x_2=1.6$

The approx. using second deg.:

$$P_{0,1,2}(1.5) = \frac{(1.5-1.0)P_{1,2} - (1.5-1.8)P_{0,1}}{(1.6-1.0)} = 0.5124715$$

$$P_{1,2,3}(1.5) = 0.5112857 \quad P_{2,3,4}(1.5) = 0.5137361$$

The higher deg. approx. are generated in a similar manner:

x_0	P_0	P_1	$P_{0,1}$	$P_{1,2}$	$P_{0,1,2}$	$P_{1,2,3}$	$P_{0,1,2,3}$	$P_{2,3,4}$	$P_{1,2,3,4}$	$P_{0,1,2,3,4}$
1.0	0.7651977									
1.3	0.6700860	0.5233449								
1.6	0.4556072	0.5102968	0.5124715							
1.9	0.2818126	0.5137361	0.5112857	0.518127						
2.2	0.1103623	0.5104270	0.5137361	0.5118302	0.5118200					

Suppose it is decided that the latest approximation $P_{0,1,2,3,4}$ is not accurate as desired. Another node x_5 can be selected, another row added to the table;

x_5 ; P_5 , $P_{4,5}$, $P_{3,4,5}$, $P_{2,3,4,5}$, $P_{1,2,3,4,5}$, $P_{0,1,2,3,4,5}$
 and $P_{0,1,2,3,4}$, $P_{1,2,3,4,5}$ and $P_{0,1,2,3,4,5}$ can be compared to determine further accuracy.

In this example, the value of the Bessel func. of the first kind of order zero at $x=2.5$ is -0.0483838 , and the new rows:

2.5 -0.0483838 0.4807699 0.5301484 0.5114070 0.5118430 0.5118277

The new entry is correct to six decimal places.

The procedure just outlined is called Neville's Method.

Let us use a practical notation:

$Q_{i,j}$ $i \geq j$: interpolating polynomial of deg. j on $(j+1)$ numbers $x_{i-j}, x_{i-j+1}, \dots, x_{i-1}, x_i$

To compute: $Q_{i,j} = P_{i-j, i-j+1, \dots, i-1, i}$

by Neville's Method, we use:

$Q_{i,j-1} = P_{i-(j-1), \dots, i-1, i}$ $Q_{i-1,j-1} = P_{i-j, i-j+1, \dots, i-1}$

$$Q_{i,j}(x) = \frac{(x-x_{i-j})Q_{i,j-1}(x) - (x-x_i)Q_{i-1,j-1}(x)}{x_i - x_{i-j}} \quad \begin{cases} j=1,2,3,\dots \\ i=j, j+1, \dots \\ Q_{i,0} = f(x_i) \end{cases}$$

x_0	$Q_{0,0}$				
x_1	$Q_{1,0}$	$Q_{1,1}$			
x_2	$Q_{2,0}$	$Q_{2,1}$	$Q_{2,2}$		
x_3	$Q_{3,0}$	$Q_{3,1}$	$Q_{3,2}$	$Q_{3,3}$	
x_4	$Q_{4,0}$	$Q_{4,1}$	$Q_{4,2}$	$Q_{4,3}$	$Q_{4,4}$

Neville's Iteration Interpolation Algorithm 3.1

Evaluation of the interpolating polynomial P on the $(n+1)$ distinct numbers x_0, \dots, x_n at the number x for the func. f .

Input; $x, x_0, \dots, x_n, f(x_0), \dots, f(x_n)$

Output; An table Q with $P(x) = Q_{n,n}$

Step 1 Do $i=1$ to n

Do $j=1$ to i

$$Q_{i,j} = \frac{(x - x_{i-j}) Q_{i,j-1} - (x - x_i) Q_{i-1,j-1}}{x_i - x_{i-j}}$$

S2 Output Q

Stop.

Stopping criterion $|Q_{i,i} - Q_{i-1,i-1}| < \epsilon$ may be used