

LECTURE #17 – SUMMARY

Work

The work done on an object by a constant force applied to it is: $W \equiv \vec{F} \cdot \Delta\vec{r}$

- units = N m = Joule (J), scalar quantity, can be positive or negative
- $W = F\Delta r \cos \theta$ where θ is the angle between \vec{F} and $\Delta\vec{r}$

If more than one force is applied to an object, then the net force is: $\vec{F}_{\text{net}} = \sum_{i=1}^N \vec{F}_i$

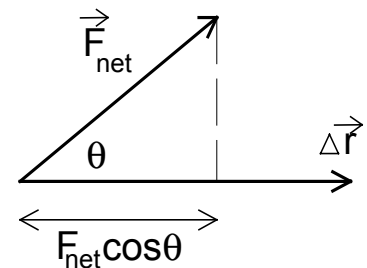
The net work done is then (= sum of the work done by each force):

$$W_{\text{net}} = \vec{F}_{\text{net}} \cdot \Delta\vec{r} = (\vec{F}_1 + \vec{F}_2 + \dots + \vec{F}_N) \cdot \Delta\vec{r} = \vec{F}_1 \cdot \Delta\vec{r} + \vec{F}_2 \cdot \Delta\vec{r} + \dots + \vec{F}_N \cdot \Delta\vec{r} = W_1 + W_2 + \dots + W_N$$

The Work-Energy Theorem ($\vec{F}_{\text{net}} \cdot \Delta\vec{r} = \frac{1}{2}mv_f^2 - \frac{1}{2}mv_i^2$) only deals with the NET FORCE. Thus $W_{\text{net}} = K_f - K_i$. This is a restatement of the Work-Energy Theorem.

"amount of work" ($\vec{F}_{\text{net}} \cdot \Delta\vec{r} = F_{\text{net}}\Delta r \cos \theta$) = magnitude of displacement
 × magnitude of force in the direction of displacement

- $W > 0$ if displacement and projected force are in the same direction, i.e., speed is increasing
- $W < 0$ if displacement and projected force are in the opposite direction, i.e., speed is decreasing



Only the component of the force in the direction of the displacement does work.

The component of $\vec{F} \parallel \vec{v} \rightarrow$ does work (and \therefore changes speed)

The component of $\vec{F} \perp \vec{v} \rightarrow$ does NO work (and \therefore does not change speed)

The Generalized Work-Energy Theorem (for non-constant forces)

Consider a general trajectory and break it into little segments for each of which the force can be treated as constant.

For the j -th segment: $W_{\text{net},j} = \vec{F}_{\text{net},j} \cdot \Delta\vec{r}_j = K_j - K_{j-1}$

As the object moves from initial position $\vec{r}_o = \vec{r}_i$ to final position $\vec{r}_N = \vec{r}_f$:

$$W_{\text{net}} = \sum_{j=1}^N (\vec{F}_{\text{net},j} \cdot \Delta\vec{r}_j) = \sum_{j=1}^N (K_j - K_{j-1}) = K_f - K_i$$

As $\Delta\vec{r}_j \rightarrow 0$: $\lim_{\Delta\vec{r}_j \rightarrow 0} \sum_{j=1}^N \vec{F}_{\text{net},j} \cdot \Delta\vec{r}_j = \int_{\vec{r}_i}^{\vec{r}_f} \vec{F}_{\text{net}} \cdot d\vec{r}$ (line integral along the trajectory)

Generalized Work-Energy Theorem

$$W_{\text{net}} = \int_{\vec{r}_i}^{\vec{r}_f} \vec{F}_{\text{net}} \cdot d\vec{r} = K_f - K_i$$

Summary of the equations derived for net work:

(1) General case :

$$W_{\text{net}} = \int_{\vec{r}_i}^{\vec{r}_f} \vec{F}_{\text{net}} \cdot d\vec{r} = K_f - K_i$$

(2) Special case - constant force:

$$W_{\text{net}} = \vec{F}_{\text{net}} \cdot \Delta\vec{r} = K_f - K_i$$

(3) Special case - constant force in 1-D (x):

$$W_{\text{net}} = F_{\text{net},x} \Delta x = K_f - K_i$$

(4) Special case - non-constant force in 1-D (x):

$$W_{\text{net}} = \int_{x_i}^{x_f} F_{\text{net},x} dx = K_f - K_i$$

Summary of the equations derived for work done by a specific force F
(not necessarily F_{net}):

(1) General case:

$$W = \int_{\vec{r}_i}^{\vec{r}_f} \vec{F} \cdot d\vec{r}$$

(2) Special case - constant force in 3-D:

$$W = \vec{F} \cdot \Delta\vec{r}$$

(3) Special case - constant force in 1-D (x):

$$W = F_x \Delta x$$

(4) Special case - non-constant force in 1-D (x):

$$W = \int_{x_i}^{x_f} F_x dx$$

Work-Energy Theorem for net work:

3-D

$$W_{\text{net}} = \int_{\vec{r}_i}^{\vec{r}_f} \vec{F}_{\text{net}} \cdot d\vec{r} = K_f - K_i$$

non-constant forces

1-D

$$W_{\text{net}} = \int_{x_i}^{x_f} F_{\text{net},x} dx = K_f - K_i$$

$$W_{\text{net}} = \vec{F}_{\text{net}} \cdot \Delta\vec{r} = K_f - K_i$$

constant forces

$$W_{\text{net}} = F_{\text{net},x} \Delta x = K_f - K_i$$

Work-Energy Theorem for work done by a specific force \vec{F} :

3-D

$$W = \int_{\vec{r}_i}^{\vec{r}_f} \vec{F} \cdot d\vec{r}$$

non-constant force \vec{F}

1-D

$$W = \int_{x_i}^{x_f} F_x dx$$

$$W = \vec{F} \cdot \Delta\vec{r}$$

constant force \vec{F}

$$W = F_x \Delta x$$