

# *Atmospheric Dynamics*

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- *Hydrodynamic Field Equations*
- *Hydrostatic Balance*
- *Log-Pressure Height*
- *P.E. for the Earths Atmosphere ( $\beta$ -plane)*
- *Geostrophic Balance and Thermal Wind Balance*
- *Conservation Properties  $\theta$  and PV*
- *Structure of  $\theta$  and PV in the Atmosphere*
- *The Utility of PV as a Diagnostic*
- *Rossby-Wave Propagation Mechanism*
- *PV Invertability and Balance*
- *QG PV and its Inversion operator*

## Hydrodynamic Field Equations

Conservation of Mass:  $\frac{D\rho}{Dt} + \rho \nabla \cdot \mathbf{u} = 0$

Conservation Momentum:  $\frac{D\mathbf{u}}{Dt} = -\frac{1}{\rho} \nabla P + \mathbf{G} + \nu \nabla^2 \mathbf{u}$

Conservation Internal Energy:  $\frac{T}{\theta} \frac{D\theta}{Dt} = \frac{J}{c_p} + \kappa \nabla^2 T + \Phi$

Equation of State:  $P = \rho R T$   $\frac{D}{Dt} \equiv \frac{\partial}{\partial t} + \mathbf{u} \cdot \nabla$

$$\nabla \equiv \left( \frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z^*} \right)$$

6 scalar equations, 6 scalar unknowns:

- $\rho$  — density  $[\text{kg m}^{-3}]$
- $\mathbf{u} = (u, v, w)$  — velocity  $[\text{m s}^{-1}]$
- $T$  — temperature  $[\text{K}^\circ]$
- $P$  — pressure  $[\text{Pa} = \text{kg m}^{-2} \text{s}^{-2}]$

$$\theta = T \left( \frac{P}{P_o} \right)^{-R/c_p}$$

$\mathbf{G}$   $[\text{m s}^{-2}]$  — Body force (e.g., gravity, Coriolis force in noninertial reference frame)

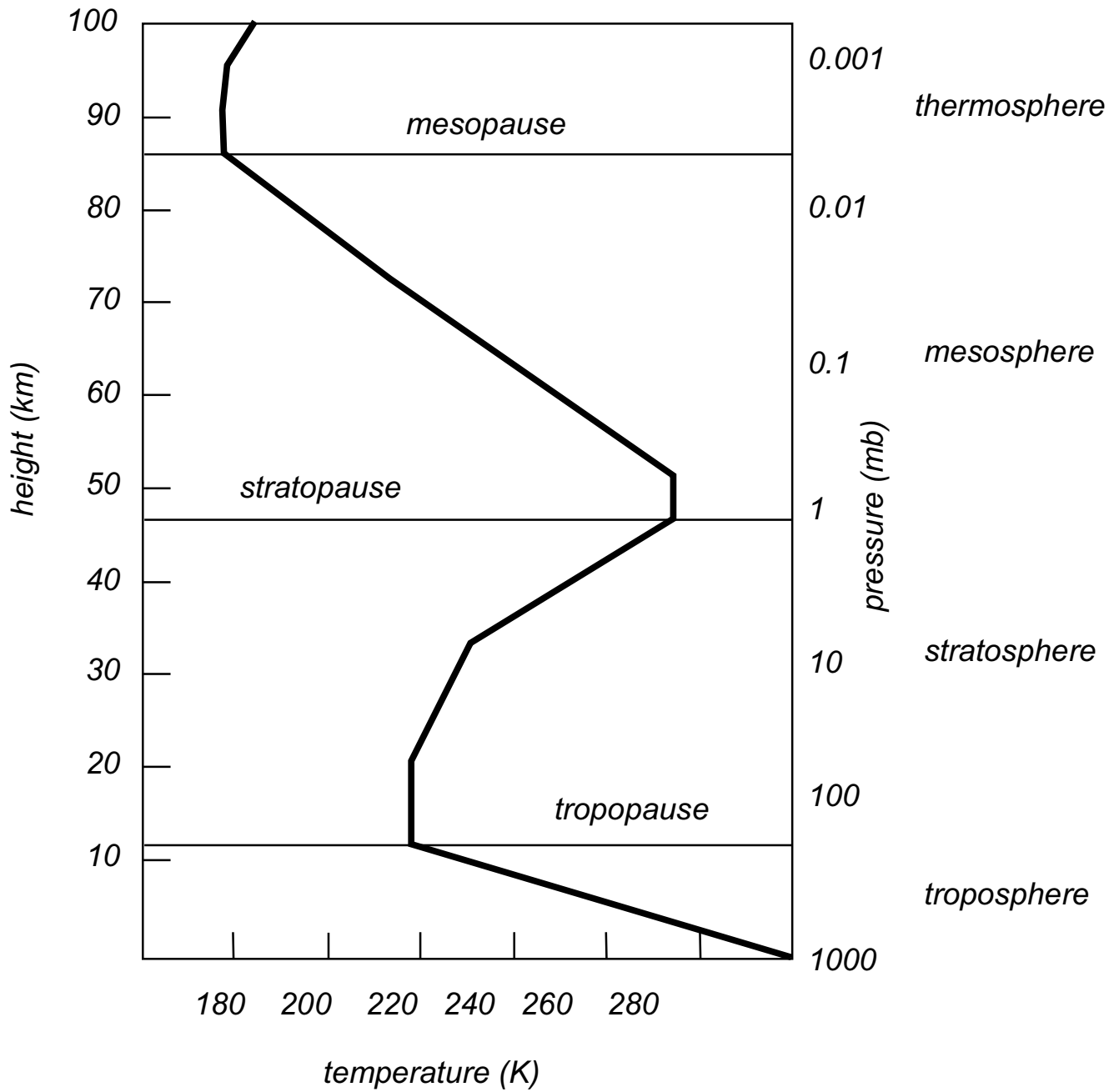
$J$   $[\text{K}^\circ \text{Kg}^{-1} \text{m}^3 \text{s}^{-1}]$  — Local heating (e.g., radiation, latent heat of condensation)

$\Phi$   $[\text{K}^\circ \text{s}^{-1}]$  — Heating by viscous friction

$\nu$   $[\text{m}^2 \text{s}^{-1}]$  — Kinematic viscosity

$\kappa$   $[\text{m}^2 \text{s}^{-1}]$  — Coefficient of thermal diffusivity

# Temperature Structure of Static Atmosphere



## Hydrostatic Balance

$$\frac{dP}{dz^*} = -\rho g$$

weight of air in column balanced by the vertical pressure gradient force

Choose  $P$  as independent vertical coordinate:  $z^* = z^*(P)$ ,  $T = T(P)$

— introduce geopotential

$$\Phi \equiv g z^*$$

$$z^* = \Phi/g \quad (\text{geopotential height})$$

$$P = \rho RT$$

$$\Rightarrow \frac{dz^*}{dP} = \frac{1}{g} \frac{d\Phi}{dP} = -\frac{RT}{Pg}$$

$$\frac{d\Phi}{d \ln P} = -RT$$

→ more intuitive if vertical pressure coordinate is expressed as a height  $z$

## Hydrostatic Balance and Log Pressure Height

$$\frac{dP}{dz^*} = -\rho g$$

$$\int_0^{z^*} dz^* = -\frac{R}{g} \int_{P_s}^P T d \ln P$$

$$P = \rho RT$$

special case:  $T = T_s$  (*const*)

$$z^* = -\frac{RT_s}{g} \ln \left( \frac{P}{P_s} \right) = -H \ln \left( \frac{P}{P_s} \right) \quad H \equiv \frac{RT_s}{g}$$

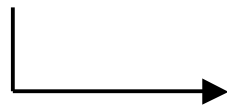
define log-pressure height:  $z \equiv -H \ln \left( \frac{P}{P_s} \right)$

$$\Rightarrow \frac{dz}{H} = -d \ln P$$

$$H \equiv RT_s/g = 7\text{km}$$

$$T_s = 240\text{K}^\circ$$

$$\frac{d\Phi}{d \ln P} = -RT$$



$$\frac{d\Phi}{dz} = \frac{RT}{H}$$

hydrostatic balance  
(log-pressure height  
vertical coordinate)

## Reference Pressure $P_o(z)$ and Density $\rho_o(z)$

→ log-pressure height may be used to derive a reference pressure profile  $P_o(z)$

$$z \equiv -H \ln \left( \frac{P}{P_s} \right) \quad H \equiv RT_s/g$$

solving for  $P$

$$P_o(z) \equiv P_s e^{-z/H}$$

ideal gas law  $P_o(z) = \rho_o(z)RT_s$

$$\rho_o(z) \equiv \rho_s e^{-z/H}$$

where  $P_s = \rho_s RT_s$

## Primitive Equations for the Earth's Atmosphere

- *spherical rotating planet (non-inertial reference frame)*  
⇒ *apparent forces ( Coriolis )*
- *completely general equations can be derived but are more complicated than required*
- *scale analysis simplifies equations*  
*e.g., hydrostatic balance dominates vertical momentum equation, can neglect Coriolis force associated with horizontal component of earth's rotation vector*
- *use a pressure vertical coordinate*  
*e.g., log-pressure height*

$$z \equiv -H \ln \left( \frac{P}{P_s} \right)$$

## Conservation of Mass / Continuity

$$\frac{D\rho}{Dt} + \rho \nabla \cdot \mathbf{u} = 0 \qquad \frac{D}{Dt} \equiv \frac{\partial}{\partial t} + \mathbf{u} \cdot \nabla$$

in pressure coordinates (Holton 1979):

$$\left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) \Big|_P + \frac{\partial \omega}{\partial P} = 0$$

$$\text{where } \omega \equiv \frac{dP}{dt} = -\rho g w^*$$

in log-pressure height coordinates:

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{1}{\rho_0} \frac{\partial \rho_0 w}{\partial z} = 0$$

where we have decompose density into reference plus deviation:

$$\rho(x, y, z) = \rho_0(z) + \rho'(x, y, z)$$

$$\text{noting that: } \rho' / \rho_0 \sim 10^{-2}$$



## Conservation of Momentum

$$\frac{D\mathbf{u}}{Dt} = -\frac{1}{\rho}\nabla P + \mathbf{G} + \nu\nabla^2\mathbf{u}$$

*horizontal component:*

*pressure gradient force*

$$\frac{1}{\rho}\left(\frac{\partial P}{\partial x} + \frac{\partial P}{\partial y}\right)\Big|_{z^*} = \left(\frac{\partial\Phi}{\partial x} + \frac{\partial\Phi}{\partial y}\right)\Big|_z$$

*Coriolis force (noninertial reference frame)*

$$f\hat{\mathbf{z}} \times \mathbf{u} = (-fv, fu, 0)$$

$f = 2\Omega \sin \phi$  — spherical geometry ( $\phi$  latitude)

$f = f_o + \beta y$  —  $\beta$ -plane (cartesian geometry)

$f = f_o$  —  $f$ -plane (cartesian geometry)

$$f_o \equiv 2\Omega \sin \phi_o \quad \beta \equiv \frac{2\Omega}{a} \cos \phi_o$$

$a$  — radius of earth

*PE horizontal momentum equations on  $\beta$ -plane*

$$\frac{Du}{Dt} - fv + \frac{\partial\Phi}{\partial x} = X$$

$$\frac{Dv}{Dt} + fu + \frac{\partial\Phi}{\partial y} = Y$$

## Conservation of Momentum

$$\frac{D\mathbf{u}}{Dt} = -\frac{1}{\rho}\nabla P + \mathbf{G} + \nu\nabla^2\mathbf{u}$$

*vertical component:*

$$\frac{Dw}{Dt} = -\frac{1}{\rho}\frac{\partial P}{\partial z^*} - g$$

scale analysis:  $10^{-7}$       10      10       $\text{m s}^{-2}$   
(midlatitude synoptic scales)

$\Rightarrow$  hydrostatic balance dominates

*PE vertical momentum equation:*

$$\frac{d\Phi}{dz} = \frac{RT}{H}$$

*hydrostatic balance  
(log-pressure height  
vertical coordinate)*

## Primitive Equations on $\beta$ -plane

$$\text{mass: } \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{1}{\rho_0} \frac{\partial \rho_0 w}{\partial z} = 0$$

$$\text{momentum: } \frac{Du}{Dt} - fv + \frac{\partial \Phi}{\partial x} = X$$
$$\frac{Dv}{Dt} + fu + \frac{\partial \Phi}{\partial y} = Y$$

$$\frac{d\Phi}{dz} = \frac{RT}{H}$$

$$\text{energy: } \frac{D\theta}{Dt} = Q$$

$$\text{state: } P = \rho RT$$

$X$   $Y$  — dissipative processes, non-conservative processes

$Q$  — diabatic heating processes (radiative, latent, chemical heating etc.) thermal conduction

## Geostrophic Balance and Thermal Wind

— scale analysis of horizontal momentum equations

midlatitude synoptic scales

$$\begin{array}{ll}
 U \sim 10 \text{ m s}^{-1} & L \sim 10^6 \text{ m} \quad (\text{horizontal}) \\
 W \sim 1 \text{ m s}^{-1} & D \sim 10^4 \text{ m} \quad (\text{vertical}) \\
 \Delta P / \rho \sim 10^3 \text{ m}^2 \text{ s}^{-2} & L/U \sim 10^5 \text{ s}
 \end{array}$$

$$\frac{Du}{Dt} - fv + \frac{\partial \Phi}{\partial x} = 0$$

$$\frac{Dv}{Dt} + fu + \frac{\partial \Phi}{\partial y} = 0$$

$$10^{-4} \quad 10^{-3} \quad 10^{-3} \quad \text{m s}^{-2}$$

→ defines geostrophic wind:

$$(u_g, v_g) \equiv \frac{1}{f_o} \left( -\frac{\partial \Phi}{\partial y}, \frac{\partial \Phi}{\partial x} \right)$$

eliminate  $\Phi$  using hydrostatic balance:  $\frac{\partial \Phi}{\partial z} = \frac{RT}{H}$

*Thermal Wind Relation:*

$$\frac{\partial u_g}{\partial z} = - \left( \frac{R}{H f_o} \right) \frac{\partial T}{\partial y}$$

$$\frac{\partial v_g}{\partial z} = \left( \frac{R}{H f_o} \right) \frac{\partial T}{\partial x}$$

Cold Pole  $\Leftrightarrow$  Fast Jet

## Material Conservation

*Adiabatic ( $Q = 0$ ) and frictionless flow ( $X = Y = 0$ )*

$$\frac{D\theta}{Dt} = 0 \quad \text{following the motion, the potential temperature is constant}$$

*$\Rightarrow$  adiabatic flow remains on constant potential temperature (isentropic) surfaces*

- very useful for tracer transport problems*

*$\theta$  is a monotonic function of height and so can be used as a vertical coordinate for fluid parcels*

*$\Rightarrow$  problem of following fluid parcel trajectories reduced from 3D to 2D*

## Material Conservation (cont)

Adiabatic ( $Q = 0$ ) and frictionless flow ( $X = Y = 0$ )

$$\frac{DPV}{Dt} = 0 \quad \text{following the motion, the potential vorticity is constant}$$

$$PV = -g \left\{ \zeta_{\theta} + f \right\} \frac{\partial \theta}{\partial P} \quad (\text{Ertel's potential vorticity})$$

$$1PVU = 10^{-6} \text{m}^2 \text{s}^{-1} \text{K kg}^{-1}$$

$$\zeta_{\theta} = \left( \frac{\partial v}{\partial x} - \frac{\partial u}{\partial y} \right) \Big|_{\theta} \quad (\text{relative vorticity})$$

$$f = 2\Omega \sin \phi \quad (\text{planetary vorticity})$$

$$-g \frac{\partial \theta}{\partial P} \quad (\text{measure of static stability})$$

- contours of  $PV$  on isentropic surface are material lines  
 $\Rightarrow$  fluid parcels are constrained to move along these lines

*Potential vorticity is a powerful dynamical tool. It's conservation provides a connection between relative vorticity, planetary vorticity, and stratification.*

*In reality, however, we know that in the real atmosphere*

$$Q \neq 0 \quad X \neq 0 \quad Y \neq 0$$

*⇒ becomes a question of the time scale of interest*

*“quasi-conservative” or “long-lived” tracer*

*PV and  $\theta$  both well conserved in lower stratosphere  
for periods of several days*

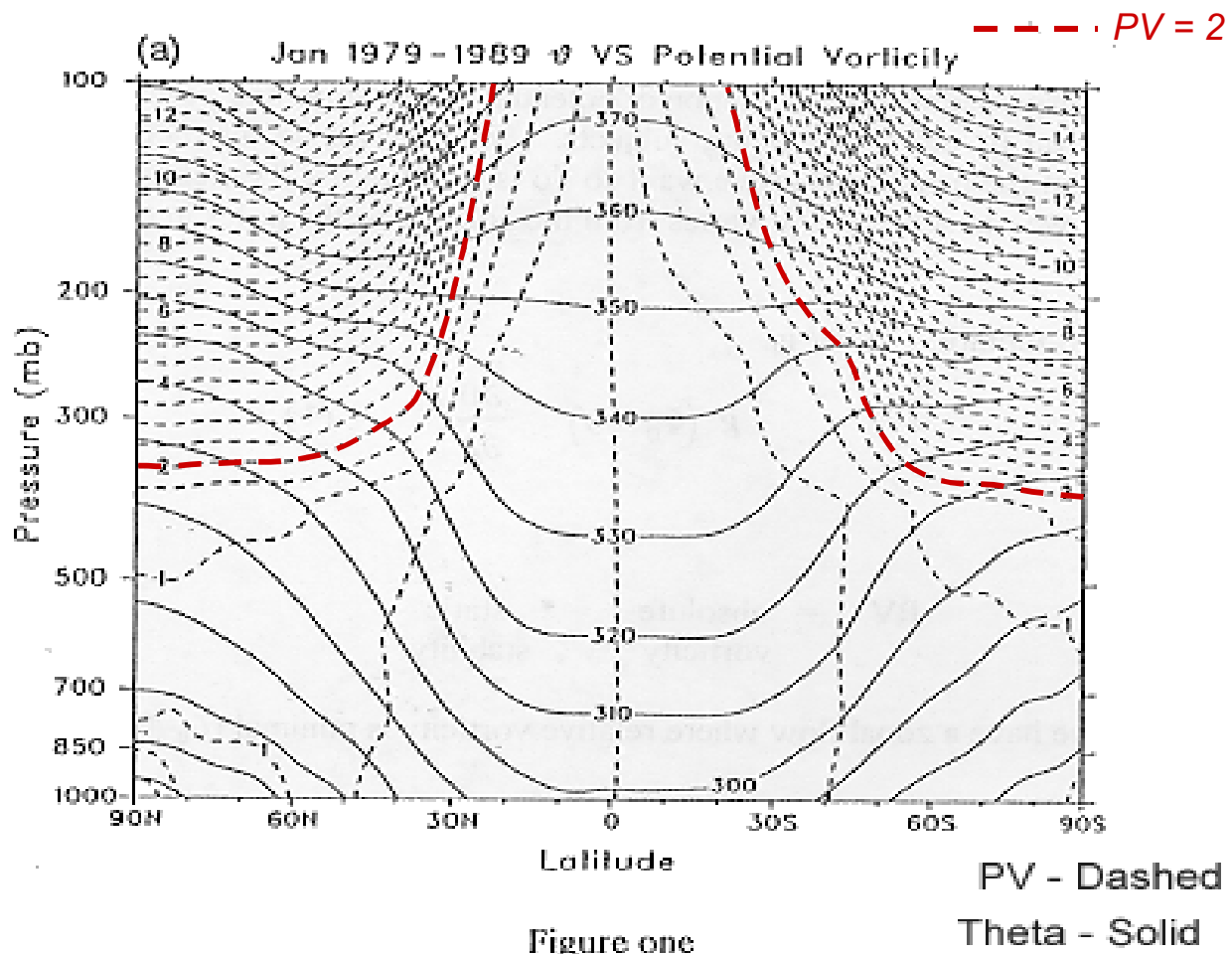
*adiabatic and frictional effects typically occur on time scales of  
weeks in this region of the atmosphere*

## Mean PV and $\theta$ distribution

$-g \frac{\partial \theta}{\partial P}$     *large in Stratosphere / small in Troposphere*

$PV$     *equator to pole increase in  $f$ , and stratification ( $\sim 300\text{mb}$ )*

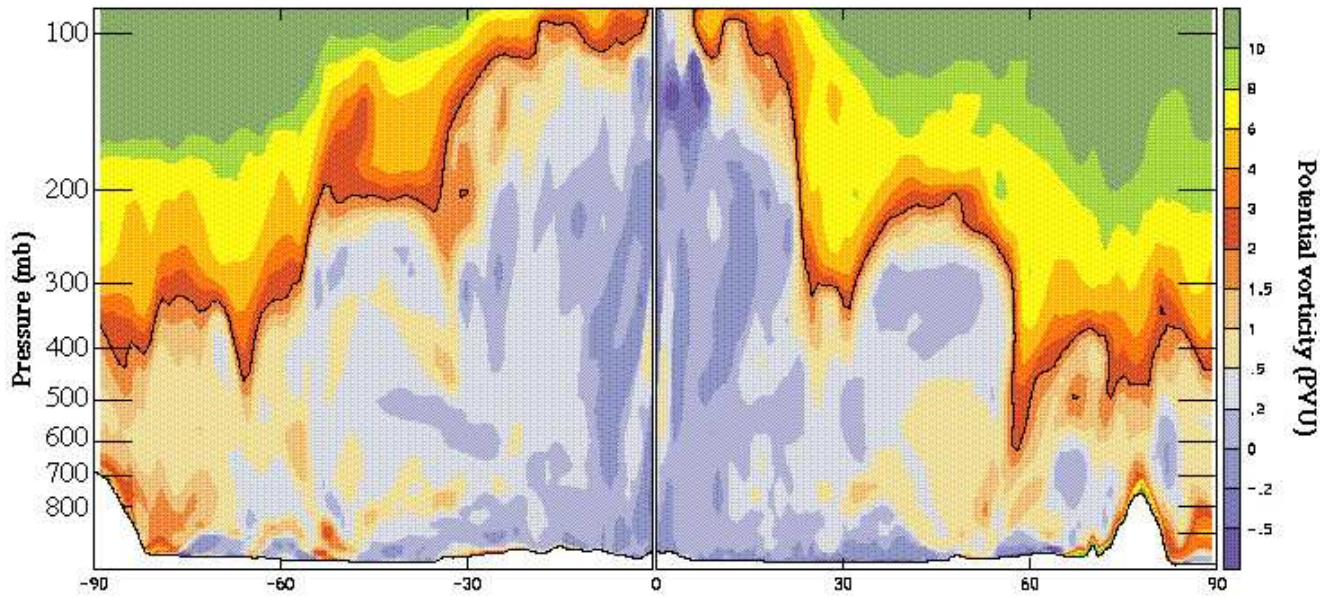
*PV = 2 surface correlates well with the extra-tropical tropopause*



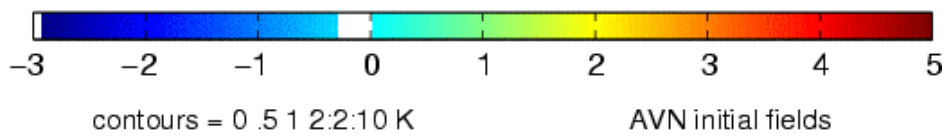
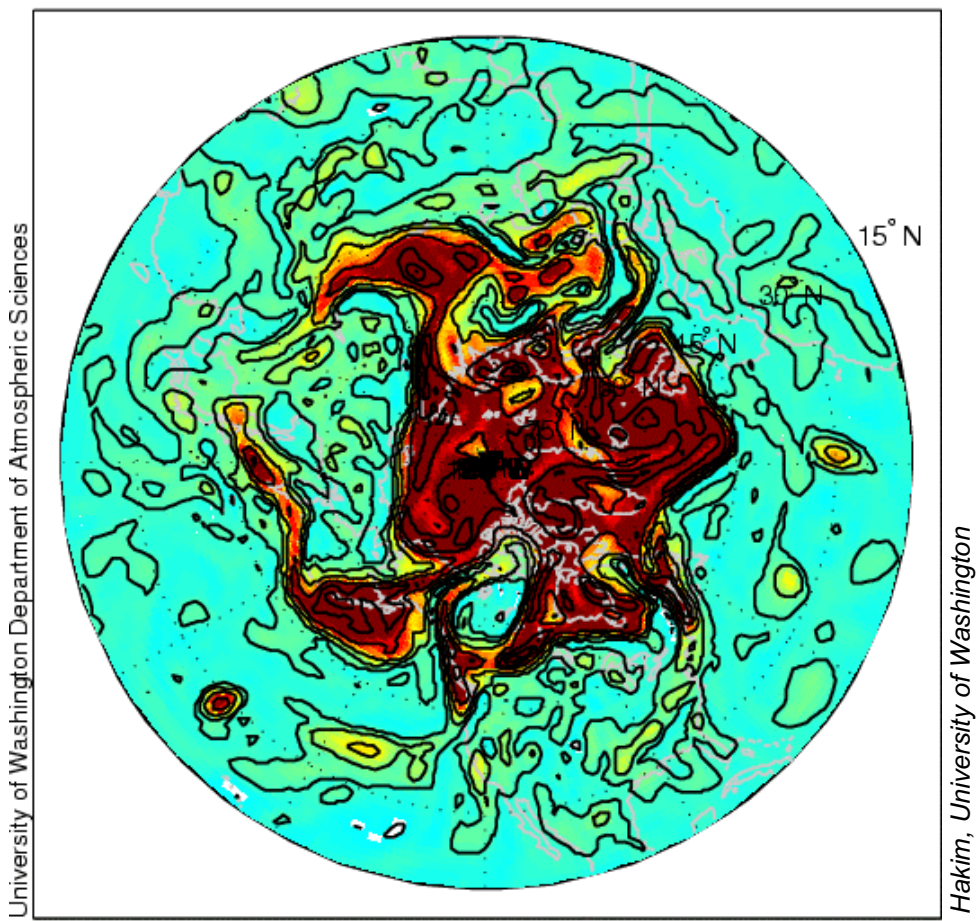


instantaneous cross section 55W

H. Wernli, ETH Zurich

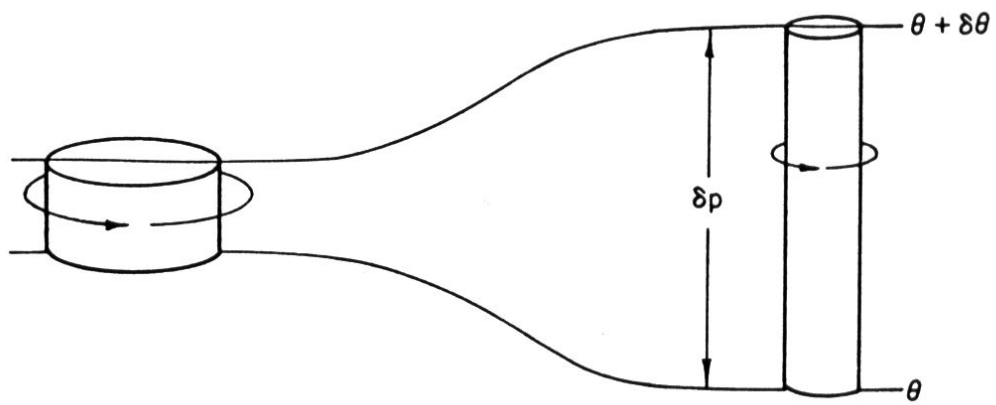


**PV on 330K 07/26/2003 0000 UTC**



# Vortex Stretching

$$PV = -g \left\{ \zeta_{\theta} + f_o \right\} \frac{\partial \theta}{\partial P}$$



Holton (1979)

$\frac{\partial \theta}{\partial P}$   $\longrightarrow$  decrease

$\zeta_{\theta}$   $\longrightarrow$  increase

# PV Conservation and North/South Displacement of Zonal Jet

– initial flow zonal (westerly or easterly)  $\Rightarrow \zeta_0 = 0$

$$\frac{\partial \theta}{\partial P} = \text{const} \Rightarrow PV = -g \left\{ \zeta + f_0 \right\} \frac{\partial \theta}{\partial P} = C \cdot f_0$$

Consider a Northward or Southward displacement of the flow

– to conserve  $PV$ ,  $\zeta$  and  $f$  must change in opposite directions

*Westerly Flow*

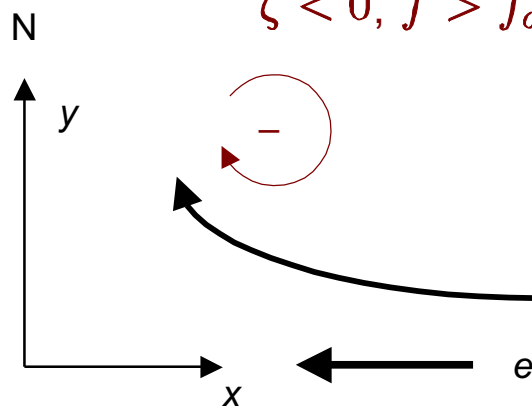
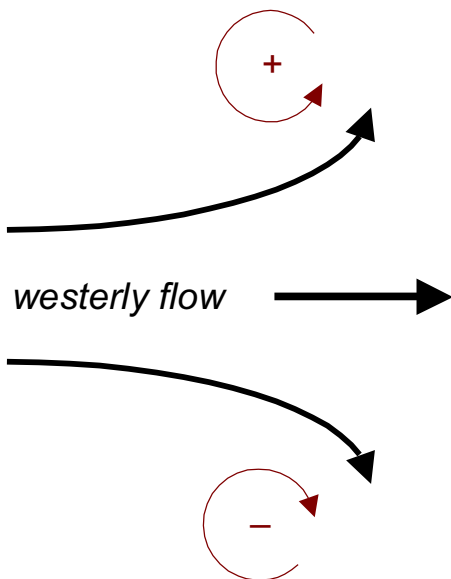
*Easterly Flow*

✗ conservation not possible

✓ conservation possible

$$\zeta > 0, f > f_0$$

$$\zeta < 0, f > f_0$$



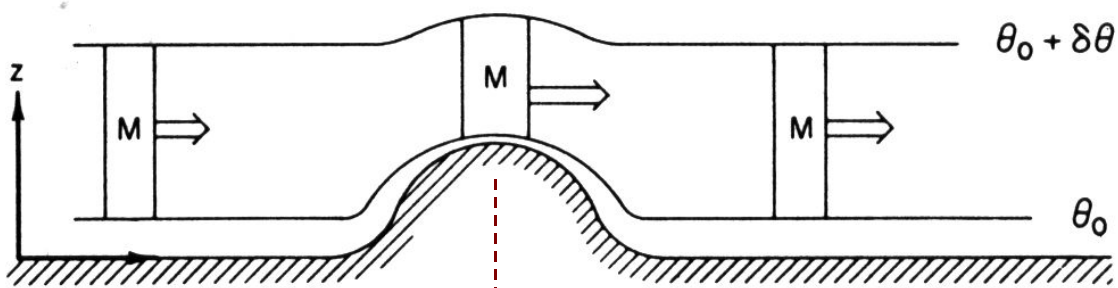
$$\zeta < 0, f < f_0$$

$$\zeta > 0, f < f_0$$

# Large-Scale Steady Topographic Flows

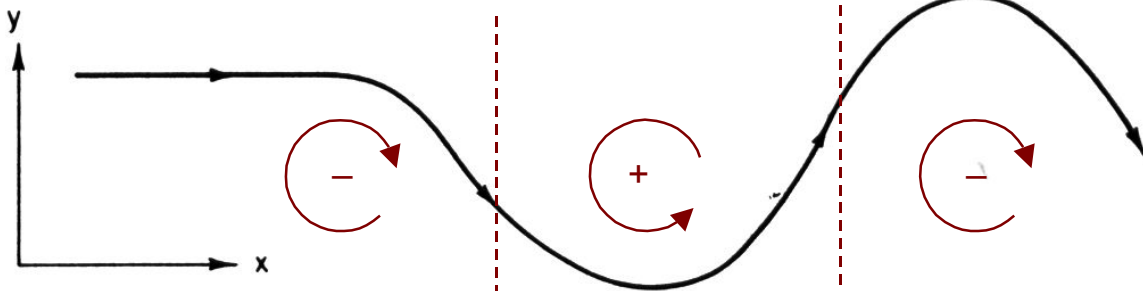
$$PV = -g \left\{ \zeta + f_o \right\} \frac{\partial \theta}{\partial P}$$

upstream:  $\zeta = 0$   
 $f = f_o$   
 $\frac{\partial \theta}{\partial P} = S$



Holton (1979)

(a)



(b)

$$\frac{\partial \theta}{\partial P} > S$$

$$\zeta < 0$$

$$f < f_o$$

$$\zeta > 0$$

$$f_{min}$$

$$\frac{\partial \theta}{\partial P} = S$$

$$\zeta = 0$$

$$f = f_o$$

$$\left. \frac{\partial \theta}{\partial P} \right|_{max}$$

$$\zeta = 0$$

$$f < f_o$$

$$\frac{\partial \theta}{\partial P} = S$$

$$\zeta = 0$$

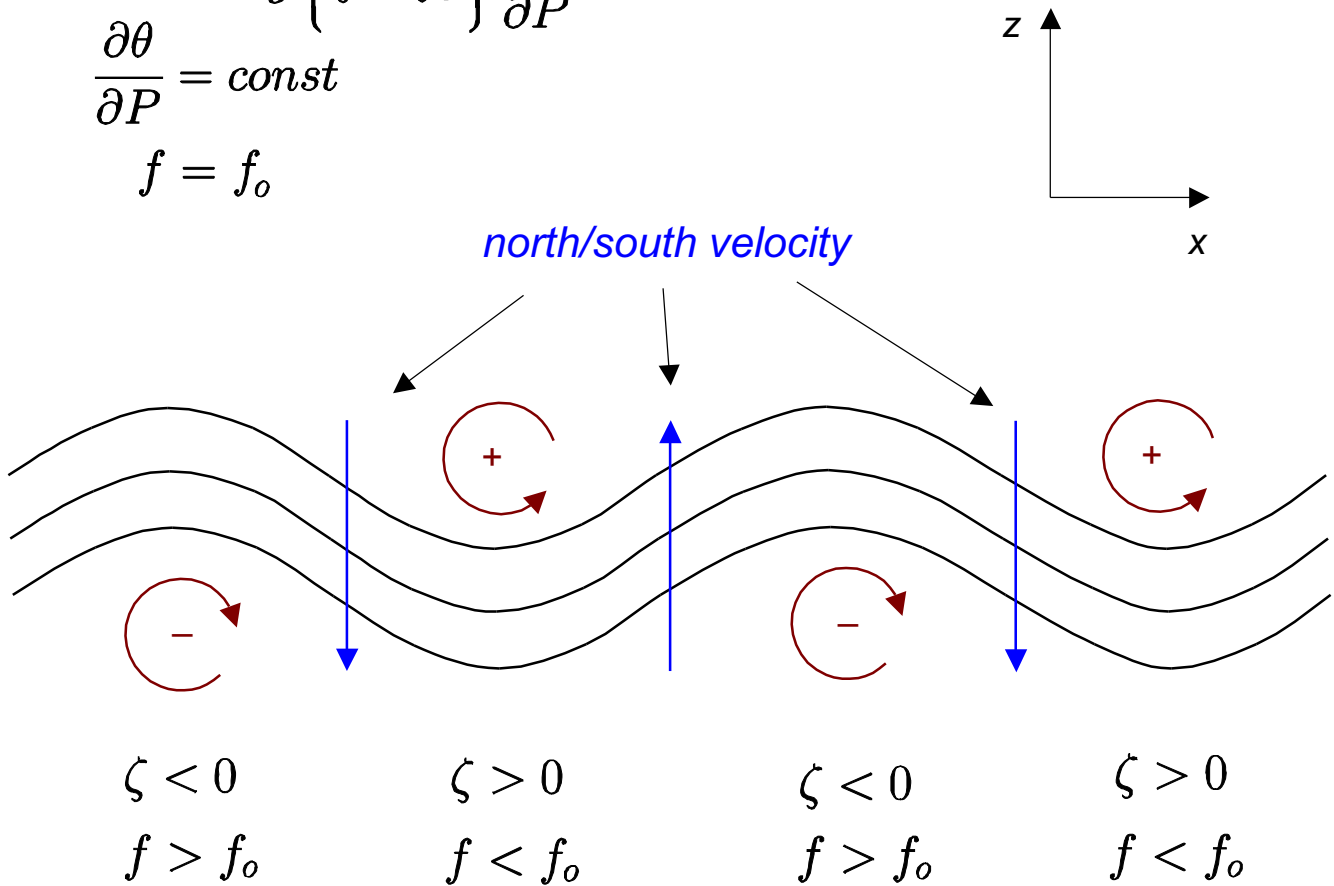
$$f = f_o$$

## Rossby-Wave Propagation Mechanism

$$PV = -g \left\{ \zeta + f_o \right\} \frac{\partial \theta}{\partial P}$$

$$\frac{\partial \theta}{\partial P} = \text{const}$$

$$f = f_o$$



*Wave pattern propagates to the west*

*⇒ Rossby waves cannot propagate to the East*

*(relative to constant background wind)*

## PV Invertability and Balance

### 1) PV Conservation or PV evolution equation

$$\frac{DPV}{Dt} = 0 \qquad \frac{D}{Dt} \equiv \frac{\partial}{\partial t} + \mathbf{u} \cdot \nabla$$

### 2) PV Invertability (balance)

– *applies to rotating stably stratified “slow” dynamics*

*i.e., Rossby waves, vortex dynamics, blocking, baroclinic and barotropic instability*

– *PV contains all dynamical information*

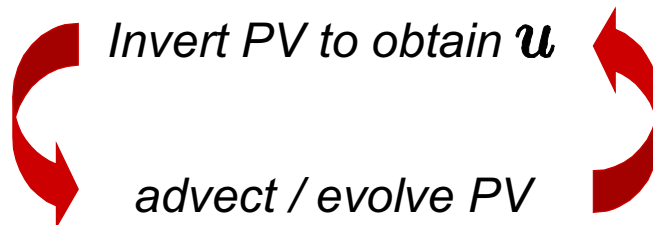
*i.e., all dynamical variables  $\mathbf{u}, T, P$  are determined by the PV distribution on an isentropic surface at every instant*

–  *$\mathbf{u}, T, P$  obtained by inversion of PV*

⇒ *Flow has fewer degrees of freedom than a fully general flow*

*Invertability  $\Leftrightarrow$  Balance*

*Balanced Integration:*



## Balance Condition/Relation

*Conditions that eliminate “fast” gravity-wave and sound-wave motion and give a complete description of the “slow” fluid motion*

*A flow is balanced if the velocity field  $\mathbf{u}$  is functionally related to the spatial distribution of mass throughout the fluid system*

*or equivalently*

*The velocity field  $\mathbf{u}$  can be deduced from the mass field diagnostically (i.e., at any instant  $t$  – no integrals or derivatives with respect to  $t$  )*

*through hydrostatic balance then,*

*knowledge of the mass  $\Rightarrow$  implies knowledge of the temperature*

*balanced system has too few degrees of freedom to describe sound waves or gravity waves*

*$\Rightarrow$  such waves are said to be “slaved” to the balanced flow or, the dynamical system is confined to a “slow manifold”*

## Quasi-Geostrophic PV Inversion Operator

*balance relation:*

$$\text{geostrophic relation: } (u_g, v_g) \equiv \frac{1}{f_o} \left( -\frac{\partial \Phi}{\partial y}, \frac{\partial \Phi}{\partial x} \right)$$

$$\text{hydrostatic balance: } \frac{\partial \Phi}{\partial z} = \frac{RT}{H}$$

*quasi-geostrophic PV:*

$$PV_g = f_o + \beta y + \left( \frac{\partial^2 \psi}{\partial x^2} + \frac{\partial^2 \psi}{\partial y^2} \right) + \rho_o^{-1} \frac{\partial}{\partial z} \left( \rho_o \frac{f_o^2}{N^2(z)} \frac{\partial \psi}{\partial z} \right)$$

where:  $\psi \equiv f_o^{-1}(\Phi - \Phi_o)$  – QG stream function



*geostrophic balance relation is lowest in hierarchy of more accurate balance relations*

*However, it highlights many important properties of PV inversion:*

$$PV_g = f_o + \beta y + \left( \frac{\partial^2 \psi}{\partial x^2} + \frac{\partial^2 \psi}{\partial y^2} \right) + \rho_o^{-1} \frac{\partial}{\partial z} \left( \rho_o \frac{f_o^2}{N^2(z)} \frac{\partial \psi}{\partial z} \right)$$

$$PV_g = \Gamma(\psi)$$

$$\text{inversion} \Rightarrow \psi = \Gamma^{-1}(PV_g)$$

*inversion is a non-local process*

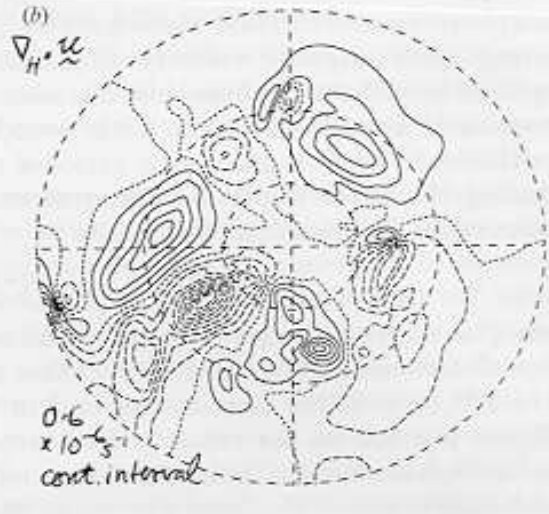
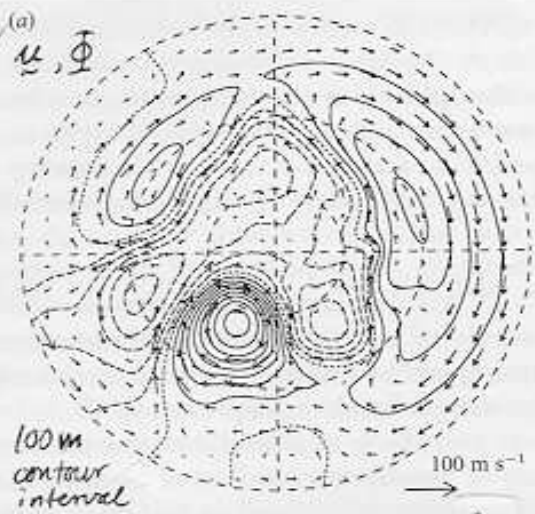
*local knowledge of PV does not imply local knowledge of  $\mathbf{u}$*

*inversion operator (elliptic) is a smoothing operator*

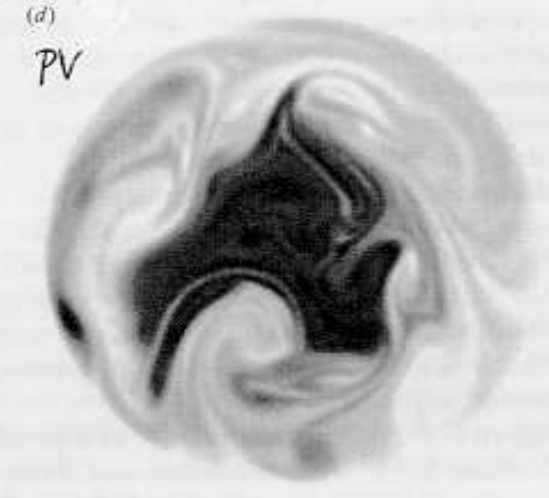
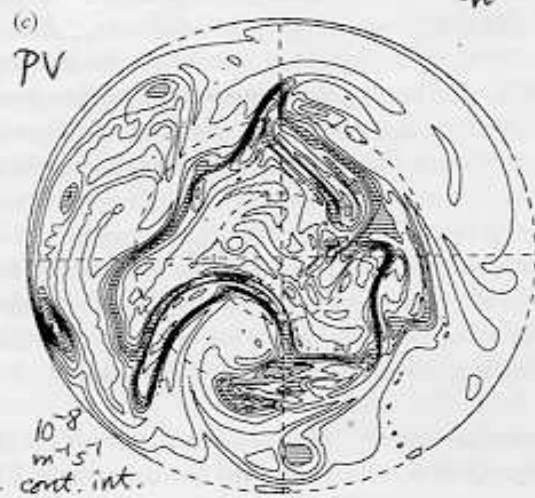
*small-scale features in PV have weak effect on  $\mathbf{u}$ , while large-scale features in PV have strong effect on  $\mathbf{u}$*

*very full literature of higher-order balance conditions and inversion operators which provide increased accuracy relative to PE solutions*

T106 PRIMITIVE-EQUATION INTEGRATION



$\hat{h} = 2 \text{ km}$



RECONSTRUCTION from PV

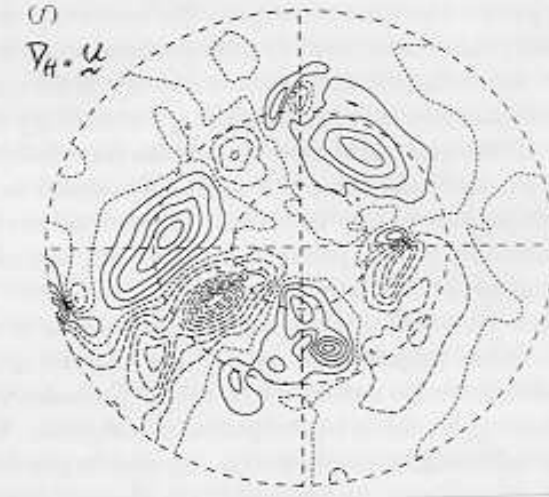
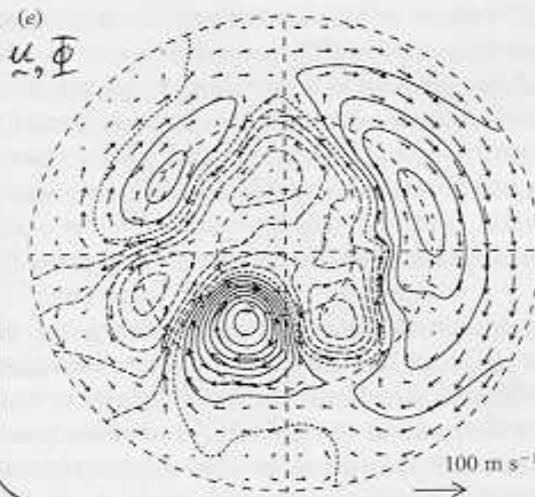
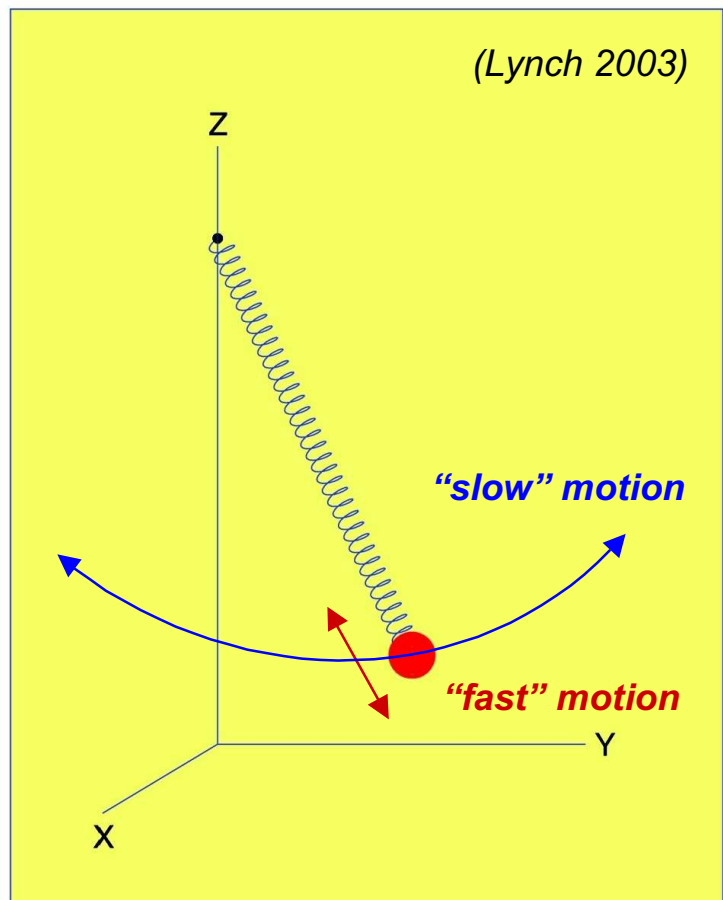


Fig. 1

*Does an exact balance condition exist?*

*Low order dynamical systems (e.g., “stiff” spring pendulum) indicate possibly **Yes**.*



*For ocean-atmosphere dynamics the answer is almost certainly **No**.*

*Time evolving balanced flows tend to radiate sound and gravity waves (“spontaneous emission”) which are, by definition, not described by balance*

## Balanced Models

- employ balance condition from the start
  - ⇒ *imposes slow manifold on the problem*
- one prognostic equation for “master variable” (e.g., PV)

### Hamiltonian balanced models

- impose balance condition as a constraint on full dynamics within Hamiltonian framework (Salmon 1988)
- Hamiltonian framework allows control over conservation principles (e.g., mass, momentum, and energy)

trade off:

*accuracy of balance model vs conservation*

### “velocity splitting” (McIntyre and Roulstone 2002)

–if one requires both accuracy **and** conservation then two velocities are required

⇒ one velocity to advect the PV and another to evaluate the PV  
(Hamiltonian models)

or

⇒ one velocity to advect the mass and another to advect the PV  
(higher-order balance models)

– two velocities differ by very little but they must differ to allow for fast dynamics